

# Fixed Point Contractive Mapping of Wardoski Type and its Application

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**Abstract:** In the paper, we introduce a new concept of soft contraction of Wardoski type which is generalization of Banach contractive condition and prove a soft fixed point theorem which generalizes Banach contraction principle in a different ways. We also give some examples which shows the validity of our results.

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## 1. Introduction

Recently, Wardowski [18] introduced a new type of contraction called F-contraction and proved a fixed point result in complete metric spaces which in turn generalizes the Banach contraction principle is the Wardowski fixed point theorem [18]. Before providing the Wardowski fixed point theorem, we recall that a self-map  $T$  on a metric space  $(X, d)$  is said to be an F-contraction if there exist  $F \in \mathcal{F}$  and  $\tau \in (0, \infty)$  such that

$$\forall x, y \in X, \quad [d(Tx, Ty) > 0 \Rightarrow \tau + F(d(Tx, Ty)) \leq F(d(x, y))], \quad (1)$$

where  $\mathcal{F}$  is the family of all functions  $F : (0, \infty) \rightarrow \mathbb{R}$  such that

(F1).  $F$  is strictly increasing, i.e. for all  $x, y \in \mathbb{R}_+$  such that  $x < y$ ,  $F(x) < F(y)$  ;

(F2). for each sequence  $\{\alpha_n\}_{n=1}^{\infty}$  of positive numbers,

$$\lim_{n \rightarrow \infty} \alpha_n = 0$$

if and only if

$$\lim_{n \rightarrow \infty} F(\alpha_n) = -\infty,$$

(F3). there exists  $k \in (0, 1)$  such that  $\lim_{\alpha \rightarrow 0^+} \alpha^k F(\alpha) = 0$  .

Obviously every F-contraction is necessarily continuous. The Wardowski fixed point theorem is given by the following theorem.

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**Theorem 1.1.** *Let  $(X, d)$  be a complete metric space and let  $T : X \rightarrow X$  be an F-contraction. Then  $T$  has a unique fixed point  $x^* \in X$  and for every  $x \in X$  the sequence  $\{T^n x\}_{n \in \mathbb{N}}$  converges to  $x^*$ .*

Later, Wardowski and Van Dung [19] have introduced the notion of an F-weak contraction and prove a fixed point theorem for F-weak contractions, which generalizes some results known from the literature. They introduced the concept of an F-weak contraction as follows.

**Definition 1.2.** *Let  $(X, d)$  be a metric space. A mapping  $T : X \rightarrow X$  is said to be an F-weak contraction on  $(X, d)$  if there exist  $F \in \mathcal{F}$  and  $\tau > 0$  such that, for all  $x, y \in X$ ,  $d(Tx, Ty) > 0 \Rightarrow \tau + F(d(Tx, Ty)) \leq F(M(x, y))$ , where*

$$M(x, y) = \max \left\{ d(x, y), d(x, Tx), d(y, Ty), \frac{d(x, Ty) + d(y, Tx)}{2} \right\}. \tag{2}$$

By using the notion of F-weak contraction, Wardowski and Van Dung [19] have proved a fixed point theorem which generalizes the result of Wardowski as follows.

**Theorem 1.3.** *Let  $(X, d)$  be a complete metric space and let  $T : X \rightarrow X$  be an F-weak contraction. If  $T$  or  $F$  is continuous, then  $T$  has a unique fixed point  $x^* \in X$  and for every  $x \in X$  the sequence  $\{T^n x\}_{n \in \mathbb{N}}$  converges to  $x^*$ .*

Recently, by adding values  $d(T^2x, x)$ ,  $d(T^2x, Tx)$ ,  $d(T^2x, y)$ ,  $d(T^2x, Ty)$  to 2, Dung and Hang [8] introduced the notion of a modified generalized F-contraction and proved a fixed point theorem for such maps. They generalized an F-weak contraction to a generalized F-contraction as follows.

**Definition 1.4.** *Let  $(X, d)$  be a metric space. A mapping  $T : X \rightarrow X$  is said to be a generalized F-contraction on  $(X, d)$  if there exist  $F \in \mathcal{F}$  and  $\tau > 0$  such that  $\forall x, y \in X$ ,  $[d(Tx, Ty) > 0 \Rightarrow \tau + F(d(Tx, Ty)) \leq F(N(x, y))]$ , where*

$$N(x, y) = \max \left\{ d(x, y), d(x, Tx), d(y, Ty), \frac{d(x, Ty) + d(y, Tx)}{2}, \frac{d(T^2x, x) + d(T^2x, Ty)}{2}, d(T^2x, Tx), d(T^2x, y), d(T^2x, Ty) \right\}.$$

By using the notion of a generalized F-contraction, Dung and Hang have proved the following fixed point theorem, which generalizes the result of Wardowski and Van Dung [19].

**Theorem 1.5.** *Let  $(X, d)$  be a complete metric space and let  $T : X \rightarrow X$  be a generalized F-contraction. If  $T$  or  $F$  is continuous, then  $T$  has a unique fixed point  $x^* \in X$  and for every  $x \in X$  the sequence  $\{T^n x\}_{n \in \mathbb{N}}$  converges to  $x^*$ .*

Very recently, Piri and Kumam [15] described a large class of functions by replacing the condition (F3) in the definition of F-contraction introduced by Wardowski with the following one:

(F3'):  $F$  is continuous on  $(0, \infty)$ .

They denote by  $\mathfrak{F}$  the family of all functions  $F : \mathbb{R}_+ \rightarrow \mathbb{R}$  which satisfy conditions (F1), (F2), and (F3'). Under this new set-up, Piri and Kumam proved some Wardowski and Suzuki type fixed point results in metric spaces as follows.

**Theorem 1.6.** *Let  $T$  be a self-mapping of a complete metric space  $X$  into itself. Suppose there exist  $F \in \mathfrak{F}$  and  $\tau > 0$  such that  $\forall x, y \in X$ ,  $[d(Tx, Ty) > 0 \Rightarrow \tau + F(d(Tx, Ty)) \leq F(d(x, y))]$ . Then  $T$  has a unique fixed point  $x^* \in X$  and for every  $x_0 \in X$  the sequence  $\{T^n x_0\}_{n=1}^\infty$  converges to  $x^*$ .*

**Theorem 1.7.** *Let  $T$  be a self-mapping of a complete metric space  $X$  into itself. Suppose there exist  $F \in \mathfrak{F}$  and  $\tau > 0$  such that  $\forall x, y \in X$ ,  $\left[ \frac{1}{2}d(x, Tx) < d(x, y) \Rightarrow \tau + F(d(Tx, Ty)) \leq F(d(x, y)) \right]$ . Then  $T$  has a unique fixed point  $x^* \in X$  and for every  $x_0 \in X$  the sequence  $\{T^n x_0\}_{n=1}^\infty$  converges to  $x^*$ .*

Beside this, the concept of soft theory as new mathematical tool for dealing with uncertainties is discussed in 1999 by Molodtsov [13]. A soft set is a collection of approximate descriptions of an object this theory has rich potential applications. On soft set theory many structures contributed by many researchers (see [5, 9, 11]). Shabir and Naz [17] were studied about soft topological spaces. In these studies, the concept of soft point is explained by different techniques. Later a different concept of soft point introduced by Das and Samanta ([6, 7]) using a different notion of soft metric space and investigated some basic properties of these spaces. Now we recall some definition which are required for the proof of our results.

**Definition 1.8.** Let  $X$  be an initial universe set and  $E$  be a set of parameters. A pair  $(F, E)$  is called a soft set over  $X$  if and only if  $F$  is a mapping from  $E$  into the set of all subsets of the set  $X$ , i.e.,  $F : E \rightarrow P(X)$  where  $P(X)$  is the power set of  $X$ .

**Definition 1.9.** Let  $VisionRes.$ ,  $\tilde{s}$  be two soft real numbers. Then the following statements hold:

- (1).  $VisionRes. \leq \tilde{s}$  if  $VisionRes. (e) \leq \tilde{s}(e)$  for all  $e \in E$ ,
- (2).  $VisionRes. \geq \tilde{s}$  if  $VisionRes. (e) \geq \tilde{s}(e)$  for all  $e \in E$ ,
- (3).  $VisionRes. < \tilde{s}$  if  $VisionRes. (e) < \tilde{s}(e)$  for all  $e \in E$ ,
- (4).  $VisionRes. > \tilde{s}$  if  $VisionRes. (e) > \tilde{s}(e)$  for all  $e \in E$ .

**Definition 1.10.** A soft set  $(F, E)$  over  $X$  is said to be a soft point, denoted by  $\tilde{x}_e$ , if for the element  $e \in E$ ,  $F(e) = \{x\}$  and  $F(\tilde{e}) = \phi$ , for all  $\tilde{e} \in E \setminus \{e\}$ .

**Definition 1.11.** Two soft points  $\tilde{x}_e, \tilde{y}_e$  are said to be equal if  $e = \tilde{e}$  and  $x = y$ . Thus  $\tilde{x}_e \neq \tilde{y}_e$  or  $e \neq \tilde{e}$ .

**Definition 1.12.** A mapping  $\tilde{d} : SP(\tilde{X}) \times SP(\tilde{X}) \rightarrow \mathbb{R}(E)^*$  is said to be a soft metric on the soft set  $\tilde{X}$  if  $\tilde{d}$  satisfies the following conditions:

- (M1).  $\tilde{d}(\tilde{x}_e, \tilde{y}_{e'}) \geq \tilde{0}$  for all  $\tilde{x}_e, \tilde{y}_{e'} \in \tilde{X}$ ,
- (M2).  $\tilde{d}(\tilde{x}_e, \tilde{y}_{e'}) \geq \tilde{0}$  if and only if  $\tilde{x}_e = \tilde{y}_{e'}$ ,
- (M3).  $\tilde{d}(\tilde{x}_e, \tilde{y}_{e'}) = \tilde{d}(\tilde{y}_{e'}, \tilde{x}_e)$  for all  $\tilde{x}_e, \tilde{y}_{e'} \in \tilde{X}$ ,
- (M4). For all  $\tilde{x}_e, \tilde{y}_{e'}, \tilde{z}_{e''} \in \tilde{X}$ ,  $\tilde{d}(\tilde{x}_e, \tilde{z}_{e''}) \leq \tilde{d}(\tilde{x}_e, \tilde{y}_{e'}) + \tilde{d}(\tilde{y}_{e'}, \tilde{z}_{e''})$ .

The soft set  $\tilde{X}$  with a soft metric  $\tilde{d}$  on  $\tilde{X}$  is called a soft metric space and denoted by  $(\tilde{X}, \tilde{d}, E)$ .

**Definition 1.13.** Let  $\{x_{e_n}^{\tilde{n}}\}$  be a sequence of soft points in a soft metric space  $(\tilde{X}, \tilde{d}, E)$ . Then the sequence  $\{x_{e_n}^{\tilde{n}}\}$  is said to be convergent in  $(\tilde{X}, \tilde{d}, E)$  if there is a soft point  $x_{e_0}^{\tilde{0}} \in \tilde{X}$  such that  $\tilde{d}(x_{e_n}^{\tilde{n}}, x_{e_0}^{\tilde{0}}) \rightarrow \tilde{0}$  as  $n \rightarrow \infty$ . This means for every  $\tilde{\epsilon} > \tilde{0}$ , chosen arbitrarily, there is a natural number  $N = N(\tilde{\epsilon})$  such that  $\tilde{0} < \tilde{d}(x_{e_n}^{\tilde{n}}, x_{e_0}^{\tilde{0}}) \leq \tilde{\epsilon}$  whenever  $n > N$ .

**Definition 1.14.** Limit of a sequence in a soft metric space, if exist, is unique.

**Definition 1.15** (Cauchy Sequence). The sequence  $\{x_{e_n}^{\tilde{n}}\}$  of soft points in  $(\tilde{X}, \tilde{d}, E)$  is called a Cauchy sequence in  $\tilde{X}$  if corresponding to every  $\tilde{\epsilon} > \tilde{0}$ , there is a  $m \in N$  such that  $\tilde{d}(x_{e_i}^{\tilde{i}}, x_{e_j}^{\tilde{j}}) \leq \tilde{\epsilon}$  for all  $i, j \geq m$  i.e.  $\tilde{d}(x_{e_i}^{\tilde{i}}, x_{e_j}^{\tilde{j}}) \rightarrow \tilde{0}$  as  $i, j \rightarrow \infty$ .

**Definition 1.16** (Complete Metric Space). The soft metric space  $(\tilde{X}, \tilde{d}, E)$  is called complete if every Cauchy Sequence in  $\tilde{X}$  converges to some point of  $\tilde{X}$ . The soft metric space  $(\tilde{X}, \tilde{d}, E)$  is called incomplete if it is not complete.

The aim of this paper is to introduce the modified generalized F-contractions, by combining the ideas of Dung and Hang [8], Piri and Kumam [15], Wardowski [18] and Wardowski and Van Dung [19] and give some soft fixed point result for these type mappings on complete soft metric space.

## 2. Main results

Let  $\mathfrak{F}_G$  denote the family of all functions  $F : \mathbb{R}_+ \rightarrow \mathbb{R}$  which satisfy conditions (F1) and (F3) and  $\mathcal{F}_G$  denote the family of all functions  $F : \mathbb{R}_+ \rightarrow \mathbb{R}$  which satisfy conditions (F1) and (F3).

**Definition 2.1.** Let  $(\tilde{X}, \tilde{d}, E)$  be a soft metric space and  $(T, \varphi) : (\tilde{X}, \tilde{d}, E) \rightarrow (\tilde{X}, \tilde{d}, E)$  be a mapping.  $(T, \varphi)$  is said to be modified generalized  $F$ -contraction of type (A) if there exist  $F \in \mathfrak{F}_G$  and  $\tau > 0$  such that

$$\tilde{x}_\lambda, \tilde{y}_\mu \in \tilde{X}, \quad [\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) > 0 \rightarrow \tau + F(\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)) \leq F(M_{(T, \varphi)}(\tilde{x}_\lambda, \tilde{y}_\mu))], \quad (3)$$

where

$$M_{(T, \varphi)}(\tilde{x}_\lambda, \tilde{y}_\mu) = \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \right. \\ \left. \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), ((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \right. \\ \left. \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\}.$$

**Remark 2.2.** Note that  $\mathfrak{F} \subseteq \mathfrak{F}_W$ . Since, for  $\beta \in (0, \infty)$ , the function  $F(\alpha) = \frac{-1}{\alpha + \beta}$  satisfies the conditions (F1) and (F3) but it does not satisfy (F2), we have  $\mathfrak{F} \subset \mathfrak{F}_W$  but  $\mathcal{F} \neq \mathcal{F}_W$ .

**Definition 2.3.** Let  $(\tilde{X}, \tilde{d}, E)$  be a soft metric space and  $(T, \varphi) : (\tilde{X}, \tilde{d}, E) \rightarrow (\tilde{X}, \tilde{d}, E)$  be a mapping.  $(T, \varphi)$  is said to be modified generalized  $F$ -contraction of type (B) if there exist  $F \in \mathcal{F}_G$  and  $\tau > 0$  such that

$$\forall \tilde{x}_\lambda, \tilde{y}_\mu \in \tilde{X}, \quad [\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) > 0 \Rightarrow \tau + F(\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)) \leq F(M_{(T, \varphi)}(\tilde{x}_\lambda, \tilde{y}_\mu)].$$

**Remark 2.4.** Note that  $\mathcal{F} \subseteq \mathcal{F}_W$ . Since, for  $\beta \in (0, \infty)$ , the function  $F(\alpha) = \ln(\alpha + \beta)$  satisfies the conditions (F1) and (F3) but it does not satisfy (F2), we have  $\mathcal{F} \subset \mathcal{F}_W$  but  $\mathcal{F} \neq \mathcal{F}_W$ .

**Remark 2.5.**

(1). Every  $F$ -contraction is a modified generalized  $F$ -contraction.

(2). Let  $(T, \varphi)$  be a modified generalized  $F$ -contraction. From 3 for all  $\tilde{x}_\lambda, \tilde{y}_\mu \in \tilde{X}$  with  $(T, \varphi)\tilde{x}_\lambda \neq (T, \varphi)\tilde{y}_\mu$ , we have

$$F(\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)) < \tau + F(\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)) \\ \leq F \left( \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \right. \right. \\ \left. \left. \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \right. \right. \\ \left. \left. \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\} \right).$$

Then, by (F1), we get

$$\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) < \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \right. \\ \left. \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \right. \\ \left. \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\},$$

for all  $\tilde{x}_\lambda, \tilde{y}_\mu \in \tilde{X}$ ,  $(T, \varphi)\tilde{x}_\lambda \neq (T, \varphi)\tilde{y}_\mu$ .

The following examples show that the inverse implication of Remark 2.5(1) does not hold.

**Example 2.6.** Let  $X = [0, 2]$  and  $E = [1, \infty)$  and define a soft metric  $d$  on  $X$  by  $d(x, y) = |x - y|$  and  $d_1(x, y) = \min\{|x - y|, 1\}$  then

$$\tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu) = \frac{1}{2}[d_1(\lambda, \mu) + d(x, y)]$$

is a soft metric space. Suppose  $\varphi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$  and let  $T : X \rightarrow X$  be given by

$$\varphi(t) = \frac{1}{2}t$$

and

$$Tx = \begin{cases} 1, & x \in [0, 2), \\ \frac{1}{2}, & x = 2. \end{cases}$$

Obviously,  $(\tilde{X}, \tilde{d}, E)$  is complete soft metric space. Since  $(T, \varphi)$  is not continuous,  $(T, \varphi)$  is not an  $F$ -contraction. For  $x \in [0, 2)$  and  $y = 2$ , we have

$$d((T, \varphi)\tilde{x}_\lambda, (T, \varphi)2) = d\left(1, \frac{1}{2}\right) = \frac{1}{2} > 0$$

and

$$\begin{aligned} & \max\left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)\tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \right. \\ & \quad \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \\ & \quad \left. \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\} \\ & \geq \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \\ & = \tilde{d}(1, 2) + \tilde{d}\left(2, \frac{1}{2}\right) \\ & = \frac{5}{2}. \end{aligned}$$

Therefore

$$\begin{aligned} d((T, \varphi)\tilde{x}_{\lambda_0}^0, (T, \varphi)2) & \leq \frac{1}{5} \max\left\{ d(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \right. \\ & \quad \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \\ & \quad \left. \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\}. \end{aligned}$$

So, by choosing  $F(\alpha) = \ln(\alpha)$  and  $\tau = \ln \frac{1}{5}$  we see that  $(T, \varphi)$  is modified generalized  $F$ -contraction of type (A) and type (B).

**Example 2.7.** Let  $X = \{-2, -1, 0, 1, 2\}$  and define a soft metric  $\tilde{d}$  on  $X$  by

$$d(x, y) = \begin{cases} 0, & \text{if } x = y, \\ 2, & \text{if } (x, y) \in \{(2, -2), (-2, 2)\}, \\ 1, & \text{otherwise.} \end{cases}$$

Then  $(\tilde{X}, \tilde{d}, E)$  is a complete soft metric space. Let  $(T, \varphi) : (\tilde{X}, \tilde{d}, E) \rightarrow (\tilde{X}, \tilde{d}, E)$  be defined by

$$(T, \varphi)(-2) = (T, \varphi)(-1) = T0 = -2, \quad (T, \varphi)1 = -1, \quad (T, \varphi)2 = 0.$$

First observe that

$$\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) > 0 \Leftrightarrow [(\tilde{x}_\lambda \in \{-2, -1, 0\} \wedge \tilde{y}_\mu = 1) \vee (\tilde{x}_\lambda \in \{-2, -1, 0\} \wedge \tilde{y}_\mu = 2) \vee (\tilde{x}_\lambda = 1, \tilde{y}_\mu = 2)].$$

Now we consider the following cases:

Case 1. Let  $\tilde{x}_\lambda \in \{-2, -1, 0\} \wedge \tilde{y}_\mu = 1$ , then

$$\begin{aligned} \tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(-2, -1) = 1, & \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu) &= \tilde{d}(\tilde{x}_\lambda, 1) = 1, & \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) &= \tilde{d}(\tilde{x}_\lambda, -2) = 0 \vee 1, \\ \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(1, -1) = 1, & \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu)}{2} &= \frac{\tilde{d}(\tilde{x}_\lambda, -1) + \tilde{d}(-2, 1)}{2} = \frac{1}{2} \vee 1, \\ \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2} &= \frac{\tilde{d}(-2, \tilde{x}_\lambda) + \tilde{d}(-2, -1)}{2} = \frac{1}{2} \vee 1, \\ d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) &= \tilde{d}(-2, -2) = 0, & d((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu) &= \tilde{d}(-2, 1) = 1, \\ \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(-2, -1) = 1, \\ d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) &= \tilde{d}(-2, -1) + \tilde{d}(\tilde{x}_\lambda, -2) = 1 \vee 2, \\ \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(-2, 1) + \tilde{d}(1, -1) = 2. \end{aligned}$$

Case 2. Let  $\tilde{x}_\lambda \in \{-2, -1, 0\} \wedge \tilde{y}_\mu = 2$ , then

$$\begin{aligned} \tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(-2, 0) = 1, & \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu) &= \tilde{d}(\tilde{x}_\lambda, 2) = 1 \vee 2, & \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) &= \tilde{d}(\tilde{x}_\lambda, -2) = 0 \vee 1, \\ \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(2, 0) = 1, & \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu)}{2} &= \frac{\tilde{d}(\tilde{x}_\lambda, 0) + \tilde{d}(-2, 2)}{2} = 1 \vee \frac{3}{2}, \\ \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2} &= \frac{\tilde{d}(-2, \tilde{x}_\lambda) + \tilde{d}(-2, 0)}{2} = \frac{1}{2} \vee 1, \\ d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) &= \tilde{d}(-2, -2) = 0, & d((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu) &= \tilde{d}(-2, 2) = 2, \\ d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(-2, 0) = 1, \\ d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) &= \tilde{d}(-2, 0) + \tilde{d}(\tilde{x}_\lambda, -2) = 1 \vee 2, \\ \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(-2, 2) + \tilde{d}(2, 0) = 3. \end{aligned}$$

Case 3. Let  $\tilde{x}_\lambda = 1 \wedge \tilde{y}_\mu = 2$ , then

$$\begin{aligned} \tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(-1, 0) = 1, & \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu) &= \tilde{d}(1, 2) = 1, & \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) &= \tilde{d}(1, -1) = 1, \\ \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(2, 0) = 1, & \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu)}{2} &= \frac{\tilde{d}(1, 0) + \tilde{d}(-1, 2)}{2} = 1, \\ \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2} &= \frac{\tilde{d}(-2, 1) + \tilde{d}(-2, 0)}{2} = 1, \\ d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) &= \tilde{d}(-2, -1) = 1, & d((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu) &= \tilde{d}(-2, 2) = 2, \\ d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(-2, 0) = 1, & d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) &= \tilde{d}(-2, 0) + \tilde{d}(1, -1) = 2, \\ \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) &= \tilde{d}(-1, 2) + \tilde{d}(2, 0) = 2. \end{aligned}$$

In Case 1, we have

$$\begin{aligned} \tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) &= \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2} \right\} \\ &= \max \left\{ \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \right. \\ &\quad \left. d((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) \right\} \\ &= 1. \end{aligned}$$

This proves that for all  $F \in \mathcal{F} \cup \mathfrak{F}$ ,  $(T, \varphi)$  is not an  $F$ -weak contraction and generalized  $F$ -contraction. Since every  $F$ -contraction is an  $F$ -weak contraction and a generalized  $F$ -contraction,  $(T, \varphi)$  is not an  $F$ -contraction. However, we see that

$$\begin{aligned} \tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) \leq & \frac{1}{2} \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \right. \\ & \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \\ & \left. \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\}. \end{aligned}$$

Hence, by choosing  $F(\alpha) = \ln(\alpha)$  and  $\tau = \ln \frac{1}{2}$  we see that  $T$  is modified generalized  $F$ -contraction of type (A) and type (B).

**Theorem 2.8.** Let  $(\tilde{X}, \tilde{d}, E)$  be a complete soft metric space and  $(T, \varphi) : (\tilde{X}, \tilde{d}, E) \rightarrow (\tilde{X}, \tilde{d}, E)$  be a modified generalized  $F$ -contraction of type (A). Then  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_\lambda^* \in \tilde{X}$  and for every  $\tilde{x}_{\lambda_0}^0 \in \tilde{X}$  the sequence  $\{T^n \tilde{x}_{\lambda_0}^0\}_{n \in \mathbb{N}}$  converges to  $\tilde{x}_{\lambda_*}^*$ .

*Proof.* Let  $\tilde{x}_{\lambda_0}^0 \in X$ . Put  $\tilde{x}_{\lambda_{n+1}}^{n+1} = T^n \tilde{x}_{\lambda_0}^0$  for all  $n \in \mathbb{N}$ . If, there exists  $n \in \mathbb{N}$  such that  $\tilde{x}_{\lambda_{n+1}}^{n+1} = \tilde{x}_{\lambda_n}^n$ , then  $(T, \varphi)\tilde{x}_{\lambda_n}^n = \tilde{x}_{\lambda_n}^n$ . That is,  $\tilde{x}_{\lambda_n}^n$  is a soft fixed point of  $(T, \varphi)$ . Now, we suppose that  $\tilde{x}_{\lambda_{n+1}}^{n+1} \neq \tilde{x}_{\lambda_n}^n$  for all  $n \in \mathbb{N}$ . Then  $\tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_n}^n) > 0$  for all  $n \in \mathbb{N}$ . It follows from (3) that, for all  $n \in \mathbb{N}$ ,

$$\begin{aligned} \tau + F(\tilde{d}((T, \varphi)\tilde{x}_{\lambda_{n-1}}^{n-1}, (T, \varphi)\tilde{x}_{\lambda_n}^n)) & \leq F \left( \max \left\{ \tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n), \frac{\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, (T, \varphi)\tilde{x}_{\lambda_n}^n) + \tilde{d}(\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_{n-1}}^{n-1})}{2}, \right. \right. \\ & \frac{\tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_{n-1}}^{n-1}) + \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_{n-1}}^{n-1}, T\tilde{x}_{\lambda_n}^n)}{2}, \\ & \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_{n-1}}^{n-1}, (T, \varphi)\tilde{x}_{\lambda_{n-1}}^{n-1}), \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n), \\ & \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_{n-1}}^{n-1}, (T, \varphi)\tilde{x}_{\lambda_n}^n) + \tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, (T, \varphi)\tilde{x}_{\lambda_{n-1}}^{n-1}), \\ & \left. \left. \tilde{d}((T, \varphi)\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n) + \tilde{d}(\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_n}^n) \right\} \right) \tag{4} \\ & = F \left( \max \left\{ \tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n), \frac{\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_{n+1}}^{n+1}) + \tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_n}^n)}{2}, \right. \right. \\ & \frac{\tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_{n-1}}^{n-1}) + \tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_{n+1}}^{n+1})}{2}, \tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_{n+1}}^{n+1}), \tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_n}^n), \\ & \left. \left. \tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_{n+1}}^{n+1}) + \tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n), \tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_n}^n) + \tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1}) \right\} \right) \\ & = F(\max\{\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n), \tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1})\}). \end{aligned}$$

If there exists  $n \in \mathbb{N}$  such that

$$\max\{\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n), \tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1})\} = \tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1})$$

then 4 becomes

$$\tau + F(\tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1})) \leq F(\tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1})).$$

Since  $\tau > 0$ , we get a contradiction. Therefore

$$\max\{\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n), \tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1})\} = \tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n), \quad \forall n \in \mathbb{N}.$$

Thus, from 4, we have

$$\begin{aligned} F(\tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1})) & = F(\tilde{d}((T, \varphi)\tilde{x}_{\lambda_{n-1}}^{n-1}, (T, \varphi)\tilde{x}_{\lambda_n}^n)) \leq F(\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n)) - \tau \\ & < F(\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n)). \end{aligned} \tag{5}$$

It follows from 5 and (F1) that

$$\tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1}) < \tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n), \quad \forall n \in \mathbb{N}.$$

Therefore  $\{\tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_n}^n)\}_{n \in \mathbb{N}}$  is a nonnegative decreasing sequence of real numbers, and hence

$$\lim_{n \rightarrow \infty} \tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_n}^n) = \gamma \geq 0.$$

Now, we claim that  $\gamma = 0$ . Arguing by contradiction, we assume that  $\gamma > 0$ . Since  $\{\tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_n}^n)\}_{n \in \mathbb{N}}$  is a nonnegative decreasing sequence, for every  $n \in \mathbb{N}$ , we have

$$\tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_n}^n) \geq \gamma. \quad (6)$$

From 6 and (F1), we get

$$\begin{aligned} F(\gamma) &\leq F(\tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, \tilde{x}_{\lambda_n}^n)) \leq F(\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n)) - \tau \\ &\leq F(\tilde{d}(\tilde{x}_{\lambda_{n-2}}^{n-2}, \tilde{x}_{\lambda_{n-1}}^{n-1})) - 2\tau \\ &\vdots \\ &\leq F(\tilde{d}(\tilde{x}_{\lambda_0}^0, \tilde{x}_{\lambda_1}^1)) - n\tau, \end{aligned} \quad (7)$$

for all  $n \in \mathbb{N}$ . Since  $F(\gamma) \in \mathbb{R}$  and  $\lim_{n \rightarrow \infty} [F(\tilde{d}(\tilde{x}_{\lambda_0}^0, \tilde{x}_{\lambda_1}^1)) - n\tau] = -\infty$ , there exists  $n_1 \in \mathbb{N}$  such that

$$F(\tilde{d}(\tilde{x}_{\lambda_0}^0, \tilde{x}_{\lambda_1}^1)) - n\tau < F(\gamma), \quad \forall n > n_1. \quad (8)$$

It follows from 7 and 8 that

$$F(\gamma) \leq F(\tilde{d}(\tilde{x}_{\lambda_0}^0, \tilde{x}_{\lambda_1}^1)) - n\tau < F(\gamma), \quad \forall n > n_1.$$

It is a contradiction. Therefore, we have

$$\lim_{n \rightarrow \infty} \tilde{d}(\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_n}^n) = \lim_{n \rightarrow \infty} \tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1}) = 0. \quad (9)$$

Simply, we can prove that  $\{\tilde{x}_{\lambda_n}^n\}_{n=1}^{\infty}$  is a Cauchy sequence. So by completeness of  $(\tilde{X}, \tilde{d}, E)$ ,  $\{\tilde{x}_{\lambda_n}^n\}_{n=1}^{\infty}$  converges to some point  $\tilde{x}_{\lambda_*}^*$  in  $\tilde{X}$ . Therefore,

$$\lim_{n \rightarrow \infty} \tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_*}^*) = 0. \quad (10)$$

Finally, we will show that  $\tilde{x}_{\lambda_*}^* = (T, \varphi)\tilde{x}_{\lambda_*}^*$ . We only have the following two cases:

$$(I) \quad \forall n \in \mathbb{N}, \exists i_n \in \mathbb{N}, i_n > i_{n-1}, i_0 = 1 \text{ and } \tilde{x}_{\lambda_{i_n+1}}^{i_n+1} = (T, \varphi)\tilde{x}_{\lambda_*}^*,$$

$$(II) \quad \exists n_3 \in \mathbb{N}, \forall n \geq n_3, \tilde{d}((T, \varphi)\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_*}^*) > 0.$$

In the first case, we have

$$\tilde{x}_{\lambda_*}^* = \lim_{n \rightarrow \infty} x_{i_{n+1}} = \lim_{n \rightarrow \infty} (T, \varphi)\tilde{x}_{\lambda_*}^* = (T, \varphi)\tilde{x}_{\lambda_*}^*.$$

In the second case from the assumption of Theorem 2.8, for all  $n \geq n_3$ , we have

$$\begin{aligned} \tau + F(\tilde{d}(\tilde{x}_{\lambda_{n+1}}^{n+1}, (T, \varphi)\tilde{x}_{\lambda_*}^*)) &= \tau + F(\tilde{d}((T, \varphi)\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_*}^*)) \\ &\leq F\left(\max\left\{\tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_*}^*), \frac{\tilde{d}(\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_*}^*) + \tilde{d}(\tilde{x}_{\lambda_*}^n, (T, \varphi)\tilde{x}_{\lambda_n}^n)}{2}, \right. \right. \\ &\quad \left. \frac{\tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_n}^n) + \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_*}^*)}{2}, \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_n}^n, T\tilde{x}_{\lambda_n}^n), \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_*}^*), \right. \\ &\quad \left. \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_*}^*) + \tilde{d}(\tilde{x}_{\lambda_n}^n, T\tilde{x}_{\lambda_n}^n), \tilde{d}((T, \varphi)\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_*}^*) + \tilde{d}(\tilde{x}_{\lambda_*}^n, (T, \varphi)\tilde{x}_{\lambda_*}^*) \right\}). \end{aligned} \quad (11)$$

From (F3), 10, and taking the limit as  $n \rightarrow \infty$  in 11, we obtain

$$\tau + F(\tilde{d}(\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{x}_{\lambda_*}^*)) \leq F(\tilde{d}(\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{x}_{\lambda_*}^*)).$$

This is a contradiction. Hence,  $\tilde{x}_{\lambda_*}^* = (T, \varphi)\tilde{x}_{\lambda_*}^*$ . Now, let us to show that  $(T, \varphi)$  has at most one soft fixed point. Indeed, if  $\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^* \in \tilde{X}$  are two distinct soft fixed points of  $(T, \varphi)$ , that is,  $vT\tilde{x}_{\lambda_*}^* = \tilde{x}_{\lambda_*}^* \neq \tilde{y}_{\lambda_*}^* = (T, \varphi)\tilde{y}_{\lambda_*}^*$ , then

$$\tilde{d}((T, \varphi)\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{y}_{\lambda_*}^*) = \tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*) > 0.$$

It follows from 3 that

$$\begin{aligned} F(\tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*)) &< \tau + F(\tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*)) \\ &= \tau + F(\tilde{d}((T, \varphi)\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{y}_{\lambda_*}^*)) \\ &\leq F\left(\max\left\{\tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*), \frac{\tilde{d}(\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{y}_{\lambda_*}^*) + \tilde{d}(\tilde{y}_{\lambda_*}^*, (T, \varphi)\tilde{x}_{\lambda_*}^*)}{2}, \right. \right. \\ &\quad \left. \frac{\tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_*}^*, \tilde{x}_{\lambda_*}^*) + \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{y}_{\lambda_*}^*)}{2}, \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{x}_{\lambda_*}^*), \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*), \right. \\ &\quad \left. \tilde{d}((T, \varphi)^2\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{y}_{\lambda_*}^*) + \tilde{d}(\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{x}_{\lambda_*}^*), \tilde{d}((T, \varphi)\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*) + \tilde{d}(\tilde{y}_{\lambda_*}^*, (T, \varphi)\tilde{y}_{\lambda_*}^*) \right\}) \\ &= F\left(\max\left\{\tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*), \frac{\tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{x}_{\lambda_0}^0\tilde{y}_{\lambda_*}^*) + \tilde{d}(\tilde{y}_{\lambda_*}^*, \tilde{x}_{\lambda_*}^*)}{2}, \frac{\tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{x}_{\lambda_*}^*) + \tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*)}{2}, \right. \right. \\ &\quad \left. \tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{x}_{\lambda_*}^*), \tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*), \tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*) + \tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{x}_{\lambda_*}^*), \tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*) + \tilde{d}(\tilde{y}_{\lambda_*}^*, \tilde{x}_{\lambda_*}^*) \right\}) \\ &= F(\tilde{d}(\tilde{x}_{\lambda_*}^*, \tilde{y}_{\lambda_*}^*)), \end{aligned} \quad (12)$$

which is a contradiction. Therefore, the soft fixed point is unique.  $\square$

**Theorem 2.9.** Let  $(\tilde{X}, \tilde{d}, E)$  be a complete soft metric space and  $(T, \varphi) : \tilde{X} \rightarrow \tilde{X}$  be a continuous modified generalized  $F$ -contraction of type  $(B)$ . Then  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_{\lambda_*}^* \in \tilde{X}$  and for every  $\tilde{x}_{\lambda} \in \tilde{X}$  the sequence  $\{(T, \varphi)^n \tilde{x}_{\lambda_0}^0\}_{n \in \mathbb{N}}$  converges to  $\tilde{x}_{\lambda_*}^*$ .

*Proof.* By using a similar method to that used in the proof of Theorem 2.8, we have

$$\begin{aligned} F(\tilde{d}(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1})) &= F(\tilde{d}((T, \varphi)\tilde{x}_{\lambda_{n-1}}^{n-1}, (T, \varphi)\tilde{x}_{\lambda_n}^n)) \leq F(\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n)) - \tau \\ &< F(\tilde{d}(\tilde{x}_{\lambda_{n-1}}^{n-1}, \tilde{x}_{\lambda_n}^n)) \end{aligned}$$

and

$$\lim_{n \rightarrow \infty} d(\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_n}^n) = \lim_{n \rightarrow \infty} d(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1}) = 0.$$

By simple calculates we can prove that  $\{\tilde{x}_{\lambda_n}^n\}_{n=1}^\infty$  is a Cauchy sequence. So, by completeness of  $(\tilde{X}, \tilde{d}, E)$ ,  $\{\tilde{x}_{\lambda_n}^n\}_{n=1}^\infty$  converges to some point  $\tilde{x}_{\lambda_*}^* \in \tilde{X}$ . Since  $(T, \varphi)$  is continuous, we have

$$\tilde{d}(\tilde{x}_{\lambda_*}^*, (T, \varphi)\tilde{x}_{\lambda_*}^*) = \lim_{n \rightarrow \infty} \tilde{d}(\tilde{x}_{\lambda_n}^n, (T, \varphi)\tilde{x}_{\lambda_n}^n) = \lim_{n \rightarrow \infty} d(\tilde{x}_{\lambda_n}^n, \tilde{x}_{\lambda_{n+1}}^{n+1}) = 0.$$

Again by using similar method as used in the proof of Theorem 2.8, we can prove that  $\tilde{x}_{\lambda_*}^*$  is the unique soft fixed point of  $(T, \varphi)$ .  $\square$

### 3. Some Applications

**Theorem 3.1.** Let  $(T, \varphi)$  be a self-mapping of a complete soft metric space  $(\tilde{X}, \tilde{d}, E)$  into itself. Suppose there exist  $F \in \mathfrak{F}$  and  $\tau > 0$  such that

$$\forall \tilde{x}_\lambda, \tilde{y}_\mu \in \tilde{X}, \quad [\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) > 0 \Rightarrow \tau + F(\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)) \lesssim F(\tilde{d}(x, y))].$$

Then  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_{\lambda_*}^* \in \tilde{X}$  and for every  $\tilde{x}_{\lambda_0}^0 \in \tilde{X}$  the sequence  $\{(T, \varphi)^n \tilde{x}_{\lambda_0}^0\}_{n=1}^{\text{inf}(T, \varphi)\tilde{y}_\mu}$  converges to  $\tilde{x}_{\lambda_*}^*$ .

*Proof.* Since

$$\begin{aligned} & \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2} \right\} \\ & \lesssim \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \frac{\tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \right. \\ & \quad \tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, \tilde{y}_\mu), \\ & \quad \left. \tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\}, \end{aligned}$$

from (F1) and Theorem 2.8 the proof is complete.  $\square$

**Theorem 3.2.** Let  $(\tilde{X}, \tilde{d}, E)$  be a complete soft metric space and let  $(T, \varphi) : \tilde{X} \rightarrow \tilde{X}$  be an  $F$ -contraction. Then  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_{\lambda_*}^* \in \tilde{X}$  and for every  $\tilde{x}_\lambda \in \tilde{X}$  the sequence  $\{(T, \varphi)^n \tilde{x}_\lambda\}_{n \in \mathbb{N}}$  converges to  $\tilde{x}_{\lambda_*}^*$ .

*Proof.* Since

$$\begin{aligned} & \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2} \right\} \\ & \lesssim \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \frac{\tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \right. \\ & \quad \tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}((T, \varphi)^2 \tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(x, (T, \varphi)\tilde{x}_\lambda), \\ & \quad \left. \tilde{d}((T, \varphi)\tilde{x}_\lambda, y) + \tilde{d}(y, (T, \varphi)\tilde{y}_\mu) \right\}. \end{aligned}$$

So from (F1) and Theorem 2.9 the proof is complete.  $\square$

**Theorem 3.3** ([19]). Let  $(\tilde{X}, \tilde{d}, E)$  be a complete soft metric space and let  $(T, \varphi) : \tilde{X} \rightarrow \tilde{X}$  be an  $F$ -weak contraction. If  $(T, \varphi)$  or  $F$  is continuous, then  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_{\lambda_*}^* \in \tilde{X}$  and for every  $\tilde{x}_\lambda \in \tilde{X}$  the sequence  $\{(T, \varphi)^n \tilde{x}_\lambda\}_{n \in \mathbb{N}}$  converges to  $\tilde{x}_{\lambda_*}^*$ .

*Proof.* Since

$$\begin{aligned} & \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2} \right\} \\ & \leq \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \right. \\ & \quad \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \tilde{d}((T, \varphi)^2x, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \\ & \quad \left. \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(x, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)\tilde{x}_\lambda, y) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\}, \end{aligned}$$

if  $F$  is continuous, from (F1) and Theorem 2.8 the proof is complete. If  $(T, \varphi)$  is continuous, from (F1) and Theorem 2.9 the proof is complete.  $\square$

**Theorem 3.4** ([8]). *Let  $(\tilde{X}, \tilde{d}, E)$  be a complete soft metric space and let  $(T, \varphi) : \tilde{X} \rightarrow \tilde{X}$  be a generalized  $F$ -contraction. If  $(T, \varphi)$  or  $F$  is continuous, then  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_{\lambda^*} \in \tilde{X}$  and for every  $\tilde{x}_\lambda \in \tilde{X}$  the sequence  $\{(T, \varphi)^n \tilde{x}_\lambda\}_{n \in \mathbb{N}}$  converges to  $\tilde{x}_{\lambda^*}$ .*

*Proof.* Since

$$\begin{aligned} & \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \right. \\ & \quad \left. \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) \right\} \\ & \leq \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \right. \\ & \quad \left. \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\}, \end{aligned}$$

if  $F$  is continuous, from (F1) and Theorem 2.8 the proof is complete. If  $(T, \varphi)$  is continuous, from (F1) and Theorem 2.9 the proof is complete.  $\square$

**Theorem 3.5.** *Let  $(\tilde{X}, \tilde{d}, E)$  be a complete soft metric space and let  $(T, \varphi) : \tilde{X} \rightarrow \tilde{X}$  be a function with the following property:*

$$\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) \leq \alpha \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu) + \beta \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda) + \gamma \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu), \quad (13)$$

where  $\alpha, \beta$ , and  $\gamma$  are nonnegative and satisfy  $\alpha + \beta + \gamma < 1$ . Then  $(T, \varphi)$  has a unique soft fixed point.

*Proof.* From 13, we have

$$\begin{aligned} \tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) & \leq (\alpha + \beta + \gamma) \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \right. \\ & \quad \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), d((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \\ & \quad \left. d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\}. \end{aligned}$$

Then if  $\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) > 0$ , we have

$$\begin{aligned} \ln \frac{1}{\alpha + \beta + \gamma} + \ln(\tilde{d}((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)) & \leq \ln \left( \max \left\{ \tilde{d}(\tilde{x}_\lambda, \tilde{y}_\mu), \frac{\tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{x}_\lambda)}{2}, \right. \right. \\ & \quad \frac{\tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{x}_\lambda) + \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)}{2}, \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)^2\tilde{x}_\lambda, \tilde{y}_\mu), \\ & \quad \left. \left. d((T, \varphi)^2\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu) + \tilde{d}(\tilde{x}_\lambda, (T, \varphi)\tilde{x}_\lambda), \tilde{d}((T, \varphi)\tilde{x}_\lambda, \tilde{y}_\mu) + \tilde{d}(\tilde{y}_\mu, (T, \varphi)\tilde{y}_\mu) \right\} \right). \end{aligned}$$

Therefore by taking  $F(\alpha) = \ln(\alpha)$  and  $\tau = \ln \frac{1}{\alpha + \beta + \gamma}$  in Theorem 2.8 or in Theorem 2.9 the proof is complete.  $\square$

**Theorem 3.6.** Let  $(T, \varphi)$  be a self-mapping of a complete soft metric space  $(\tilde{X}, \tilde{d}, E)$  into itself and an  $F$ -contraction. Then  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_{\lambda_*}^* \in \tilde{X}$  and for every  $\tilde{x}_{\lambda_0}^0 \in \tilde{X}$  the sequence  $\{(T, \varphi)^n \tilde{x}_{\lambda_0}^0\}_{n=0}^{\infty}$  converges to  $\tilde{x}_{\lambda_*}^*$ .

**Theorem 3.7.** Let  $(T, \varphi)$  be a self-mapping of a complete soft metric space  $(\tilde{X}, \tilde{d}, E)$  into itself. Suppose  $F \in \mathcal{F}$  and there exists  $\tau > 0$  such that  $\forall \tilde{x}_\lambda, \tilde{y}_\mu \in \tilde{X}, \{d(Tx, Ty) > 0 \implies \tau + F(d((T, \varphi)\tilde{x}_\lambda, (T, \varphi)\tilde{y}_\mu)) \leq F(d(\tilde{x}_\lambda, \tilde{y}_\mu))\}$ . Then  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_{\lambda_*}^* \in \tilde{X}$  and for every  $\tilde{x}_{\lambda_0}^0 \in \tilde{X}$  the sequence  $\{(T, \varphi)^n \tilde{x}_{\lambda_0}^0\}_{n=0}^{\infty}$  converges to  $\tilde{x}_{\lambda_*}^*$ .

**Theorem 3.8.** Let  $(\tilde{X}, \tilde{d}, E)$  be a complete soft metric space and  $T : \tilde{X} \rightarrow \tilde{X}$  be an  $F$ -weak contraction. If  $(T, \varphi)$  or  $F$  is continuous, then we have

- (1).  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_{\lambda_*}^* \in \tilde{X}$ .
- (2). For all  $\tilde{x}_\lambda \in \tilde{X}$ , the sequence  $\{(T, \varphi)^n \tilde{x}_\lambda\}$  is convergent to  $\tilde{x}_{\lambda_*}^*$ .

**Theorem 3.9.** Let  $(\tilde{X}, \tilde{d}, E)$  be a complete soft metric space and  $T : \tilde{X} \rightarrow \tilde{X}$  be a generalized  $F$ -contraction. If  $(T, \varphi)$  or  $F$  is continuous, then we have

- (1).  $(T, \varphi)$  has a unique soft fixed point  $\tilde{x}_{\lambda_*}^* \in \tilde{X}$ .
- (2). For each  $\tilde{x}_\lambda \in \tilde{X}$ , if  $(T, \varphi)^{n+1} \tilde{x}_\lambda = (T, \varphi)^n \tilde{x}_\lambda$  for all  $n \in \mathbb{N} \cup \{0\}$ , then  $\lim_{n \rightarrow \infty} (T, \varphi)^n \tilde{x}_\lambda = \tilde{x}_{\lambda_*}^*$ .

## 4. Conclusion

Our theorems are extensions of the above theorems in the following aspects:

- (1). Theorem 2.8 gives all consequences of Theorem 3.7, without assumption (F2) used in its proof.
- (2). Theorem 2.9 gives all consequences of Theorem 3.6, without assumption (F2) used in its proof.
- (3). If in Theorem 3.9,  $F$  is continuous, Theorem 2.8 gives all consequences of Theorem 3.9, without assumptions (F2) and (F3) used in its proof.
- (4). If in Theorem 3.9,  $(T, \varphi)$  is continuous, Theorem 2.9 gives all consequences of Theorem 3.9 without assumption (F2) used in its proof.
- (5). Because every  $F$ -weak contraction is a generalized  $F$ -contraction, 3 and 4 are also true for Theorem 3.8.

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