

Estimating the Approximate Solutions of the Fornberg-Whitham and Oskolkov-Benjamin-Bona-Mahony Equations

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Abstract: In this paper we study the initial value problems of Fornberg-Whitham(FW) and Oskolkov-Benjamin-Bona-Mahony(OBBM) equations which are locally wellposed in the Sobolev space H^s for $s > \frac{3}{2}$. we define the approximate solutions of FW and OBBM equations and compute the errors. Then we estimate the H^σ -norm of this errors.

Keywords: Sobolev space, Approximate solutions, Well-posedness, Non-local form.

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1. Introduction

The Fornberg-Whitham(FW) equation introduced as a model to study breaking of non-linear dispersive water waves. In mathematical physics, the Whitham equation is a non-local model for non-linear dispersive waves. We consider the initial value problem for the Fornberg-Whitham equation

$$u_{xxt} - u_t + \frac{9}{2}u_x u_{xx} + \frac{3}{2}u u_{xxx} - \frac{3}{2}u u_x + u_x = 0 \quad (1)$$

$$u(x, 0) = u_0(x), x \in T, t \in \mathbb{R}$$

where $u(x, t)$ is the fluid velocity, t is the time and x is the spatial co-ordinate. The FW equation was written by Fornberg and Whitham in 1978 as a model for breaking waves. The FW equation can be (and is more conveniently) written in the following non-local form

$$u_t + \frac{3}{2}u u_x = (1 - \partial_x^2)^{-1} \partial_x u \quad (2)$$

The non-local form can be obtained from FW equation as follows,

$$u_{xxt} - u_t + \frac{9}{2}u_x u_{xx} + \frac{3}{2}u u_{xxx} - \frac{3}{2}u u_x + u_x = 0$$

$$u_t + \frac{3}{2}u u_x - u_{txx} - \frac{3}{2}[u u_{xxx} + 3u_x u_{xx}] = \partial_x u$$

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$$u_t + \frac{3}{2}uu_x - u_{txx} - \frac{3}{2}\frac{\partial}{\partial x}\left[\frac{\partial}{\partial x}(uu_x)\right] = \partial_x u$$

$$\left(1 - \frac{\partial^2}{\partial x^2}\right)\left(u_t + \frac{3}{2}uu_x\right) = \partial_x u$$

Multiply bothsides by $(1 - \partial_x^2)^{-1}$, we get

$$u_t + \frac{3}{2}uu_x = (1 - \partial_x^2)^{-1}\partial_x u$$

Next, We consider the initial value problem (i.v.p) of the Oskolkov-Benjamin-Bona-Mahony Equation

$$u_t - u_x - u_{xxt} + uu_x = 0 \quad (3)$$

$$u(x, 0) = u_0(x), x \in T, t \in \mathbb{R}$$

The OBBM equation derived from the water wave model. Non-local form of the OBBM Equation can be written as,

$$u_t + uu_x = (1 - \partial_x^2)^{-1}\partial_x(u - u_x^2 - uu_{xx}) \quad (4)$$

The non-local form can be obtained from OBBM equation as follows. Adding and subtracting the terms uu_{xxx} and $3u_x u_{xx}$, we get

$$u_t - u_x - u_{xxt} + uu_x + uu_{xxx} - uu_{xxx} + 3u_x u_{xx} - 3u_x u_{xx} = 0$$

$$(1 - \partial_x^2)(u_t + uu_x) = u_x - 3u_x u_{xx} - uu_{xxx}$$

$$u_t + uu_x = (1 - \partial_x^2)^{-1}\partial_x(u - u_x^2 - uu_{xx})$$

Written this way, the FW and OBBM equations are become a special case in the family of nonlinear wave equations of the form

$$u_t + auu_x = L(u)$$

This work studies the initial value problems of FW and OBBM equations. The paper is structured as follows. In section 1 we give the introduction and preliminaries. In section 2 we define approximate solutions and compute the error, while in section 3 we estimate the H^σ -norm of this error.

1.1. Preliminaries

Lemma 1.1. *Let $\sigma \in \mathbb{R}$. If $\lambda \in Z^+$ and $\lambda \gg 1$ then*

$$\| \cos(\lambda x - \alpha) \|_{H^\sigma(T)} \approx \lambda^\sigma, \quad \alpha \in \mathbb{R}$$

The above relation is also true if $\cos(\lambda x - \alpha)$ is replaced by $\sin(\lambda x - \alpha)$. Finally, for any $s \geq 0$ we have

$$\|u^{\omega, \lambda}(t)\|_{H^\sigma(T)} = \|\omega \lambda^{-1} + \lambda^{-s} \cos(\lambda x - \omega t)\|_{H^\sigma(T)}$$

$$\|u^{\omega, \lambda}(t)\|_{H^\sigma(T)}^\sigma \leq \lambda^{-1} + \lambda^{-s+\sigma}$$

where $\lambda \gg 1$.

Definition 1.2. For any $s \in \mathbb{R}$ the operator $D^s = (1 - \partial^2 x)^{\frac{s}{2}}$ is defined by

$$\widehat{D^s f}(\xi) = (1 + \xi^2)^{\frac{s}{2}} \hat{f}(\xi),$$

where $\hat{f}$ is the Fourier transform

$$\hat{f}(\xi) = \int_T e^{-ix\xi} f(x) dx$$

The inverse relation is given by

$$f(x) = \frac{1}{2\pi} \sum_{\xi \in \mathbb{Z}} \hat{f}(\xi) e^{ix\xi}$$

Then, for $f \in H^s(T)$ we have

$$\begin{aligned} \|f\|_{H^s(T)}^2 &= \frac{1}{2\pi} \sum_{\xi \in \mathbb{Z}} (1 + \xi^2)^s |\hat{f}(\xi)|^2 \\ &= \|D^s f\|_{L^2(T)}^2 \end{aligned}$$

2. Approximate FW and OBBM Solutions

We shall consider approximate solutions of the form

$$u^{\omega, \lambda}(x, t) = \omega \lambda^{-1} + \lambda^{-s} \cos(\lambda x - \omega t) \quad (5)$$

Where ω is bounded subset of $\mathbb{R}$ and λ is in the set of positive integers $\mathbb{Z}^+$. Next, we compute the error of the approximate solution of (4). Differentiating (4) with respect to t ,

$$\begin{aligned} \partial_t u^{\omega, \lambda} &= 0 + \lambda^{-s} (-\sin(\lambda x - \omega t))(-\omega) \\ \partial_t u^{\omega, \lambda} &= \omega \lambda^{-s} \sin(\lambda x - \omega t) \end{aligned} \quad (6)$$

Differentiating (4) with respect to x ,

$$\begin{aligned} \partial_x u^{\omega, \lambda} &= 0 + \lambda^{-s} (-\sin(\lambda x - \omega t))(\lambda) \\ &= -\lambda \lambda^{-s} \sin(\lambda x - \omega t) \\ \partial_x u^{\omega, \lambda} &= -\lambda^{-s+1} \sin(\lambda x - \omega t) \end{aligned} \quad (7)$$

Approximate FW Solutions: Substituting (6) and (7) into the Burgers part of the FW equation, we get

$$\begin{aligned} \partial_t u^{\omega, \lambda} + \frac{3}{2} u^{\omega, \lambda} \partial_x u^{\omega, \lambda} &= \omega \lambda^{-s} \sin(\lambda x - \omega t) + \frac{3}{2} [\omega \lambda^{-1} + \lambda^{-s} \cos(\lambda x - \omega t)] [-\lambda^{-s+1} \sin(\lambda x - \omega t)] \\ &= \omega \lambda^{-s} \sin(\lambda x - \omega t) - \frac{3}{2} \omega \lambda^{-s} \sin(\lambda x - \omega t) - \frac{3}{2} \lambda^{-2s+1} \cos(\lambda x - \omega t) \sin(\lambda x - \omega t) \\ &= \frac{-1}{2} \omega \lambda^{-s} \sin(\lambda x - \omega t) - \frac{3}{4} \lambda^{-2s+1} \sin 2(\lambda x - \omega t) \\ &= F_1 + F_2 \end{aligned}$$

Next, we compute the error resulting from applying the non-local perturbation part of the FW equation to the approximate solution. That is, we form the quantity $(1 - \partial_x^2)^{-1} \partial_x u^{\omega, \lambda}$. We shall write this term by using the operator D^s .

$$[-(1 - \partial_x^2)^{-1}] \partial_x u^{\omega, \lambda} = [-D^{-2} \partial_x (\omega \lambda^{-1} + \lambda^{-s} \cos(\lambda x - \omega t))]$$

$$\begin{aligned}
 &= D^{-2}\lambda^{-s+1}\sin(\lambda x - \omega t) \\
 &= F_3
 \end{aligned}$$

To summarize the error F of the approximate solution (5) is,

$$F = \partial_t u^{\omega,\lambda} + \frac{3}{2}u^{\omega,\lambda}\partial_x u^{\omega,\lambda} - D^{-2}\partial_x u^{\omega,\lambda} \quad (8)$$

$$= F_1 + F_2 + F_3 \quad (9)$$

Where F_j are defined as above.

Approximate OBBM Solutions: we substituting (6) and (7) into the Burgers part of the OBBM equation we get,

$$\begin{aligned}
 \partial_t u^{\omega,\lambda} + u^{\omega,\lambda}\partial_x u^{\omega,\lambda} &= \omega\lambda^{-s}\sin(\lambda x - \omega t) + [\omega\lambda^{-1} + \lambda^{-s}\cos(\lambda x - \omega t)][-\lambda^{-s+1}\sin(\lambda x - \omega t)] \\
 &= \omega\lambda^{-s}\sin(\lambda x - \omega t) - \omega\lambda^{-s}\sin(\lambda x - \omega t) - \lambda^{-2s+1}\cos(\lambda x - \omega t)\sin(\lambda x - \omega t) \\
 &= \lambda^{-2s+1}\cos(\lambda x - \omega t)\sin(\lambda x - \omega t) \\
 \partial_t u^{\omega,\lambda} + u^{\omega,\lambda}\partial_x u^{\omega,\lambda} &= -\frac{1}{2}\lambda^{-2s+1}\sin 2(\lambda x - \omega t) \\
 &= F_1
 \end{aligned}$$

Next, we compute the error resulting from applying the non local perturbation part of the OBBM equation to the approximate solution. That is we form the quantity

$$\begin{aligned}
 -(1 - \partial_x^2)^{-1}\partial_x(u - u_x^2 - uu_{xx}) &= -D^{-2}\partial_x(u^{\omega,\lambda} - (u_x^{\omega,\lambda})^2 - u^{\omega,\lambda}u_{xx}^{\omega,\lambda}) \\
 &= -D^{-2}\partial_x(u^{\omega,\lambda} + D^{-2}\partial_x(u_x^{\omega,\lambda})^2 + D^{-2}\partial_x(u^{\omega,\lambda}u_{xx}^{\omega,\lambda}))
 \end{aligned}$$

Now consider

$$\begin{aligned}
 -D^{-2}\partial_x(u^{\omega,\lambda}) &= -D^{-2}(-\lambda^{-s+1})\sin(\lambda x - \omega t) \\
 &= D^{-2}(\lambda^{-s+1})\sin(\lambda x - \omega t) \\
 &= F_2
 \end{aligned}$$

Now consider

$$\begin{aligned}
 (\partial_x(u^{\omega,\lambda}))^2 &= (-\lambda^{-s+1}\sin(\lambda x - \omega t))^2 \\
 &= \lambda^{-2s+2}\sin^2(\lambda x - \omega t) \\
 &= \lambda^{-2s+2}\left[\frac{1}{2} - \frac{1}{2}\cos 2(\lambda x - \omega t)\right] \\
 \partial_x(\partial_x(u^{\omega,\lambda}))^2 &= \lambda^{-2s+2}\left[0 - \frac{1}{2}(-\sin 2(\lambda x - \omega t))2\lambda\right] \\
 &= \lambda^{-2s+2}\lambda\sin 2(\lambda x - \omega t) \\
 &= \lambda^{-2s+3}\sin 2(\lambda x - \omega t)
 \end{aligned}$$

Therefore

$$D^{-2}\partial_x(\partial_x(u^{\omega,\lambda}))^2 = D^{-2}\lambda^{-2s+3}\sin 2(\lambda x - \omega t)$$

$$= F_3$$

Now consider $D^{-2}\partial_x(u^{\omega,\lambda}u_{xx}^{\omega,\lambda})$

$$\begin{aligned} u_{xx}^{\omega,\lambda} &= -\lambda^{-s+1}\cos(\lambda x - \omega t)\lambda \\ &= -\lambda^{-s+2}\cos(\lambda x - \omega t) \\ u^{\omega,\lambda}u_{xx}^{\omega,\lambda} &= [\omega\lambda^{-1} + \lambda^{-s}\cos(\lambda x - \omega t)][-\lambda^{-s+2}\cos(\lambda x - \omega t)] \\ &= -\omega\lambda^{-s+1}\cos(\lambda x - \omega t) - \lambda^{-2s+2}\left[\frac{1}{2} + \frac{1}{2}\cos 2(\lambda x - \omega t)\right] \end{aligned}$$

Since $\cos^2\theta = \frac{1}{2} + \frac{1}{2}\cos 2\theta$

$$\begin{aligned} \partial_x(u^{\omega,\lambda}u_{xx}^{\omega,\lambda}) &= -\omega\lambda^{-s+1}(-\sin(\lambda x - \omega t)\lambda) + 0 - \lambda^{-2s+2}\left(\frac{1}{2}(-\sin 2(\lambda x - \omega t)2\lambda)\right) \\ \partial_x(u^{\omega,\lambda}u_{xx}^{\omega,\lambda}) &= \omega\lambda^{-s+2}(\sin(\lambda x - \omega t)) + \lambda^{-2s+3}\sin 2(\lambda x - \omega t) \\ D^{-2}\partial_x(u^{\omega,\lambda}u_{xx}^{\omega,\lambda}) &= D^{-2}\omega\lambda^{-s+2}\sin(\lambda x - \omega t) + D^{-2}\lambda^{-2s+3}\sin 2(\lambda x - \omega t) \\ &= F_4 + F_5 \end{aligned}$$

To summarize, the error F of the approximate solution (5) is

$$F = F_1 + F_2 + F_3 + F_4 + F_5 \quad (10)$$

Where F_j 's are derived as above.

3. Estimating the Error of Approximate solutions of FW and OBBM equations

Next we shall estimate the H^σ -norm of the error F in (9) and (10) by estimating separately the H^σ norm of each term F_j .

Estimating the H^σ -norm of error of FW equation:

Estimating the H^σ -norm of F_1

$$\begin{aligned} \|F_1(t)\|_{H^\sigma(T)} &= \left\| \frac{-1}{2}\omega\lambda^{-s}\sin(\lambda x - \omega t) \right\|_{H^\sigma(T)} \\ &= \frac{1}{2}\omega\lambda^{-s}\|\sin(\lambda x - \omega t)\|_{H^\sigma(T)} \\ &\leq \frac{1}{2}\omega\lambda^{-s+\sigma} \end{aligned}$$

since by Lemma 1.1, $\lambda \gg 1$.

Estimating the H^σ -norm of F_2

$$\begin{aligned} \|F_2(t)\|_{H^\sigma(T)} &= \left\| -\frac{3}{4}\lambda^{-2s+1}\sin 2(\lambda x - \omega t) \right\|_{H^\sigma(T)} \\ &= \frac{3}{4}\lambda^{-2s+1}\|\sin 2(\lambda x - \omega t)\|_{H^\sigma(T)} \\ &\leq \frac{3}{4}\lambda^{-2s+1+\sigma} \end{aligned}$$

since by Lemma 1.1, $\lambda \gg 1$.

Estimating the H^σ -norm of F_3

$$\begin{aligned}
 \|F_3(t)\|_{H^\sigma(T)} &= \|D^{-2}\lambda^{-s+1}\sin(\lambda x - \omega t)\|_{H^\sigma(T)} \\
 &= \|\lambda^{-s+1}\sin(\lambda x - \omega t)\|_{H^{\sigma-2}(T)} \\
 &\leq \lambda^{-s+1}\|\sin(\lambda x - \omega t)\|_{H^{\sigma-2}(T)} \\
 &\leq \lambda^{-s+1}\lambda^{\sigma-2} \\
 &= \lambda^{-s+\sigma-1}
 \end{aligned}$$

since by Lemma 1.1, $\lambda \gg 1$. Putting the above estimates together gives the following H^σ -estimate for the error of the FW approximate solution.

$$\|F\|_{H^\sigma(T)} \leq \frac{1}{2}\omega\lambda^{-s+\sigma} + \frac{3}{4}\lambda^{-2s+1+\sigma} + \lambda^{-s+\sigma-1} \quad (11)$$

Estimating the H^σ -norm of error of OBBM equation: Next we shall estimate the H^σ -norm of the error F in (6) by estimating separately the H^σ norm of each term F_j .

Estimating the H^σ -norm of F_1

$$\begin{aligned}
 \|F_1(t)\|_{H^\sigma(T)} &= \left\| -\frac{1}{2}\lambda^{-2s+1}\sin 2(\lambda x - \omega t) \right\|_{H^\sigma(T)} \\
 &= \frac{1}{2}\lambda^{-2s+1}\|\sin 2(\lambda x - \omega t)\|_{H^\sigma(T)} \\
 &\leq \frac{1}{2}\lambda^{-2s+1}\lambda^\sigma \\
 &\leq \lambda^{-2s+\sigma+1}
 \end{aligned}$$

since by Lemma 1.1, $\lambda \gg 1$.

Estimating the H^σ -norm of F_2

$$\begin{aligned}
 \|F_2(t)\|_{H^\sigma} &= \|D^{-2}\lambda^{-s+1}\sin(\lambda x - \omega t)\|_{H^\sigma} \\
 &= \lambda^{-s+1}\|\sin(\lambda x - \omega t)\|_{H^{\sigma-2}} \\
 &\leq \lambda^{-s+1+\sigma}
 \end{aligned}$$

Estimating the H^σ -norm of F_3

$$\begin{aligned}
 \|F_3(t)\|_{H^\sigma} &= \|D^{-2}\lambda^{-2s+3}\sin 2(\lambda x - \omega t)\|_{H^\sigma} \\
 &= \lambda^{-2s+3}\|D^{-2}\sin 2(\lambda x - \omega t)\|_{H^\sigma} \\
 &= \lambda^{-2s+3}\|\sin 2(\lambda x - \omega t)\|_{H^{\sigma-2}} \\
 &\leq \lambda^{-2s+3+\sigma}
 \end{aligned}$$

since by Lemma 1.1, $\lambda \gg 1$.

Estimating the H^σ -norm of F_4

$$\|F_4(t)\|_{H^\sigma} = \|D^{-2}\omega\lambda^{-s+2}\sin(\lambda x - \omega t)\|_{H^\sigma}$$

$$\begin{aligned}
 &= \omega \lambda^{-s+2} \| D^{-2} \sin(\lambda x - \omega t) \|_{H^\sigma} \\
 &= \omega \lambda^{-s+2} \| \sin(\lambda x - \omega t) \|_{H^{\sigma-2}} \\
 &\leq \omega \lambda^{-s+2+\sigma}
 \end{aligned}$$

since by Lemma 1.1, $\lambda \gg 1$.

Estimating the H^σ -norm of F_5

$$\begin{aligned}
 \| F_5(t) \|_{H^\sigma} &= \| D^{-2} \lambda^{-2s+3} \sin 2(\lambda x - \omega t) \|_{H^\sigma} \\
 &= \lambda^{-2s+3} \| D^{-2} \sin 2(\lambda x - \omega t) \|_{H^\sigma} \\
 &= \lambda^{-2s+3} \| \sin 2(\lambda x - \omega t) \|_{H^{\sigma-2}} \\
 &\leq \lambda^{-2s+3+\sigma}
 \end{aligned}$$

since by Lemma 1.1, $\lambda \gg 1$. Now putting the above estimates together gives the following H^σ -Estimate for the error of the OBBM approximate solution.

$$\| F(t) \|_{H^\sigma} \leq \lambda^{-2s+1+\sigma} + \lambda^{-s+1+\sigma} + \lambda^{-2s+3+\sigma} + \omega \lambda^{-s+2+\sigma} + \lambda^{-2s+3+\sigma} \quad (12)$$

Hence, we derived the approximate solutions of FW and OBBM equations and compute the error of the approximate solution of FW and OBBM equation. Also we estimated the H^σ norm of the error.

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