



# Invariant Submanifold of $(4k, 2k)$ Structure Manifold

Research Article

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**Abstract:** In this paper, we have studied various properties of a  $(4k, 2k)$  structure manifold and its invariant submanifold, where  $k$  is positive integer. Under two different assumptions, the nature of induced structure  $\psi$ , has also been discussed.

**Keywords:** Invariant submanifold, Nijenhuis tensor, projection operators and complementary distributions.

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## 1. Introduction

Let  $V^m$  be a  $C^\infty$   $m$ -dimensional Riemannian manifold imbedded in a  $C^\infty$   $n$ -dimensional Riemannian manifold  $M^n$ , where  $m < n$ . The imbedding being denoted by

$$f : V^m \longrightarrow M^n$$

Let  $B$  be the mapping induced by  $f$  i.e.  $B=df$

$$df : T(V) \longrightarrow T(M)$$

Let  $T(V, M)$  be the set of all vectors tangent to the submanifold  $f(V)$ . It is well known that

$$B : T(V) \longrightarrow T(V, M)$$

Is an isomorphism. The set of all vectors normal to  $f(V)$  forms a vector bundle over  $f(V)$ , which we shall denote by  $N(V, M)$ . We call  $N(V, M)$  the normal bundle of  $V^m$ . The vector bundle induced by  $f$  from  $N(V, M)$  is denoted by  $N(V)$ . We denote by  $C : N(V) \longrightarrow N(V, M)$  the natural isomorphism and by  $\eta_s^r(V)$  the space of all  $C^\infty$  tensor fields of type  $(r, s)$  associated with  $N(V)$ . Thus  $\zeta_0^0(V) = \eta_0^0(V)$  is the space of all  $C^\infty$  functions defined on  $V^m$  while an element of  $\eta_0^1(V)$  is a  $C^\infty$  vector field normal to  $V^m$  and an element of  $\zeta_0^1(V)$  is a  $C^\infty$  vector field tangential to  $V^m$ .

Let  $\bar{X}$  and  $\bar{Y}$  be vector fields defined along  $f(V)$  and  $\tilde{X}, \tilde{Y}$  be the local extensions of  $\bar{X}$  and  $\bar{Y}$  respectively. Then  $[\tilde{X}, \tilde{Y}]$  is a vector field tangential to  $M^n$  and its restriction  $[\tilde{X}, \tilde{Y}] / f(V)$  to  $f(V)$  is determined independently of the choice of these local extension  $\tilde{X}$  and  $\tilde{Y}$ . Thus  $[\bar{X}, \bar{Y}]$  is defined as

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$$[\bar{X}, \bar{Y}] = [\tilde{X}, \tilde{Y}] / f(V) \quad (1)$$

Since  $B$  is an isomorphism

$$[BX, BY] = B[X, Y] \text{ for all } X, Y \in \zeta_0^1(V) \quad (2)$$

Let  $\tilde{G}$  be the Riemannian metric tensor of  $M^n$ , we define  $g$  and  $g^*$  on  $V^m$  and  $N(V)$  respectively as

$$g(X_1, X_2) = \tilde{G}(BX_1, BX_2) \text{ f, and} \quad (3)$$

$$g^*(N_1, N_2) = \tilde{G}(CN_1, CN_2) \quad (4)$$

For all  $X_1, X_2 \in \zeta_0^1(V)$  and  $N_1, N_2 \in \eta_0^1(V)$ . It can be verified that  $g$  and  $g^*$  are the induced metrics on  $V^m$  and  $N(V)$  respectively. Let  $\tilde{\nabla}$  be the Riemannian connection determined by  $\tilde{G}$  in  $M^n$ , then  $\tilde{\nabla}$  induces a connection  $\nabla$  in  $f(V)$  defined by

$$\nabla_{\bar{X}} \bar{Y} = \tilde{\nabla}_{\tilde{X}} \tilde{Y} / f(V) \quad (5)$$

where  $\bar{X}$  and  $\bar{Y}$  are arbitrary  $C^\infty$  vector fields defined along  $f(V)$  and tangential to  $f(V)$ . Let us suppose that  $M^n$  is a  $(4k, 2k)$  structure manifold with structure tensor  $\tilde{\psi}$  of type  $(1, 1)$  satisfying

$$\tilde{\psi}^{4k} + \tilde{\psi}^{2k} = 0 \quad (6)$$

Let  $\tilde{L}$  and  $\tilde{M}$  be the complementary distributions corresponding to the projection operators

$$\tilde{l} = -\tilde{\psi}^{2k}, \quad \tilde{m} = I + \tilde{\psi}^{2k} \quad (7)$$

where  $I$  denotes the identity operator. From and , we have

$$(a) \tilde{l} + \tilde{m} = I; (b) \tilde{l}^2 = \tilde{l}; (c) \tilde{m}^2 = \tilde{m}; (d) \tilde{l}\tilde{m} = \tilde{m}\tilde{l} = 0 \quad (8)$$

Let  $D_l$  and  $D_m$  be the subspaces inherited by complementary projection operators  $l$  and  $m$  respectively. We define

$$D_l = \{X \in T_p(V) : lX = X, mX = 0\}$$

$$D_m = \{X \in T_p(V) : mX = X, lX = 0\}$$

Thus  $T_p(V) = D_l + D_m$ . Also  $\text{Ker } l = \{X : lX = 0\} = D_m$ ;  $\text{Ker } m = \{X : mX = 0\} = D_l$  at each point  $p$  of  $f(V)$ .

## 2. Invariant Submanifold of $(4k, 2k)$ Structure Manifold

We call  $V^m$  to be invariant submanifold of  $M^n$  if the tangent space  $T^p(f(V))$  of  $f(V)$  is invariant by the linear mapping  $\tilde{\psi}$  at each point  $p$  of  $f(V)$ . Thus

$$\tilde{\psi}BX = B\psi X, \quad (9)$$

for all  $X \in \zeta_0^1(V)$  and  $\psi$  being a  $(1, 1)$  tensor field in  $V^m$ .

**Theorem 2.1.** *Let  $\tilde{N}$  and  $N$  be the Nijenhuis tensors determined by  $\tilde{\psi}$  and  $\psi$  in  $M^n$  and  $V^m$  respectively, then*

$$\tilde{N} (BX, BY) = BN (X, Y), \text{ for all } X, Y \in \zeta_0^1 (V). \quad (10)$$

*Proof.* We have, by using (2) and (10)

$$\begin{aligned} \tilde{N} (BX, BY) &= [\tilde{\psi}BX, \tilde{\psi}BY] + \tilde{\psi}^2 [BX, BY] - \tilde{\psi} [\tilde{\psi}BX, BY] - \tilde{\psi} [BX, \tilde{\psi}BY] \\ &= [B\psi X, B\psi Y] + \tilde{\psi}^2 B [X, Y] - \tilde{\psi} [B\psi X, BY] - \tilde{\psi} [BX, B\psi Y] \\ &= B [\psi X, \psi Y] + B\psi^2 [X, Y] - \tilde{\psi} B [\psi X, Y] - \tilde{\psi} B [X, \psi Y] \\ &= B \{ [\psi X, \psi Y] + \psi^2 [X, Y] - \psi [\psi X, Y] - \psi [X, \psi Y] \} \\ &= BX + B\psi^3 X \end{aligned} \quad (11)$$

□

### 3. Distribution $\tilde{M}$ Never Being Tangential to $f(V)$

**Theorem 3.1.** *If the distribution  $\tilde{M}$  is never tangential to  $f(V)$ , then*

$$\tilde{m} (BX) = 0 \text{ for all } X \in \zeta_0^1 (V) \quad (12)$$

and the induced structure  $\psi$  on  $V^m$  satisfies

$$\psi^{2k} = -I. \quad (13)$$

*Proof.* If possible  $\tilde{m} (BX) \neq 0$ . From (10) we get

$$\tilde{\psi}^{2k} BX = B\psi^{2k} X; \quad (14)$$

from (1) and (14)

$$\begin{aligned} \tilde{m} (BX) &= (I + \tilde{\psi}^{2k}) BX \\ &= BX + B\psi^{2k} X \\ \tilde{m} (BX) &= B [X + \psi^{2k} X] \end{aligned} \quad (15)$$

This relation shows that  $\tilde{m} (BX)$  is tangential to  $f(V)$  which contradicts the hypothesis. Thus  $\tilde{m} (BX) = 0$ . Using this result in (15) and remembering that  $B$  is an isomorphism, we get  $\psi^{2k} = -I$ . □

**Theorem 3.2.** *Let  $\tilde{M}$  be never tangential to  $f(V)$ , then*

$$\tilde{N}_{\tilde{m}} (BX, BY) = 0. \quad (16)$$

*Proof.* We have

$$\tilde{N}_{\tilde{m}} (BX, BY) = [\tilde{m} BX, \tilde{m} BY] + \tilde{m}^2 [BX, BY] - \tilde{m} [\tilde{m} BX, BY] - \tilde{m} [BX, \tilde{m} BY] \quad (17)$$

Using (2), (8) (c) and (12), we get (16). □

**Theorem 3.3.** Let  $\tilde{M}$  be never tangential to  $f(V)$ , then

$$\tilde{N}_i(BX, BY) = 0. \quad (18)$$

*Proof.* We have

$$\tilde{N}_i(BX, BY) = [\tilde{l}BX, \tilde{l}BY] + \tilde{l}^2[BX, BY] - \tilde{l}[\tilde{l}BX, BY] - \tilde{l}[BX, \tilde{l}BY] \quad (19)$$

Using (2), (8) (a), (b) and (12) in (19); we get (18)  $\square$

**Theorem 3.4.** Let  $\tilde{M}$  be never tangential to  $f(V)$ . Define

$$\tilde{H}(\tilde{X}, \tilde{Y}) = \tilde{N}(\tilde{X}, \tilde{Y}) - \tilde{N}(\tilde{m}\tilde{X}, \tilde{Y}) - \tilde{N}(\tilde{X}, \tilde{m}\tilde{Y}) + \tilde{N}(\tilde{m}\tilde{X}, \tilde{m}\tilde{Y}) \quad (20)$$

For all  $\tilde{X}, \tilde{Y} \in \zeta_0^1(M)$ , then

$$\tilde{H}(BX, BY) = BN(X, Y). \quad (21)$$

*Proof.* Using  $\tilde{X} = BX$ ,  $\tilde{Y} = BY$  and (11), (12) in (20), we get (21).  $\square$

## 4. Distribution $\tilde{M}$ Always Being Tangential to $f(V)$

**Theorem 4.1.** Let  $\tilde{M}$  be always tangential to  $f(V)$ , then

$$(a) \tilde{m}(BX) = BmX; (b) \tilde{l}(BX) = BlX. \quad (22)$$

*Proof.* From (15), We get (22) (a). Also

$$l = -\psi^{2k} \quad (23)$$

$$lX = -\psi^{2k}X$$

$$BlX = -B\psi^{2k}X \quad (24)$$

Using (10) in (24)

$$BlX = -\tilde{\psi}^{2k}BX = \tilde{l}(BX), \quad (25)$$

which is (22) (b).  $\square$

**Theorem 4.2.** Let  $\tilde{M}$  be always tangential to  $f(V)$ , then  $l$  and  $m$  satisfy

$$(a) l + m = I; (b) lm = ml = 0; (c) l^2 = l; (d) m^2 = m. \quad (26)$$

*Proof.* Using (8) and (22) We get the results.  $\square$

**Theorem 4.3.** If  $\tilde{M}$  is always tangential to  $f(V)$ , then

$$\psi^{4k} + \psi^{2k} = 0. \quad (27)$$

*Proof.* From (10)

$$\tilde{\psi}^{4k} BX = B \psi^{4k} X \quad (28)$$

Using (1) in (28)

$$\begin{aligned} -\tilde{\psi}^{2k} BX &= B \psi^{4k} X \\ -B \psi^{2k} X &= B \psi^{4k} X \text{ or} \\ \psi^{4k} + \psi^{2k} &= 0 \end{aligned}$$

which is (27). □

**Theorem 4.4.** *If  $\tilde{M}$  Is always tangential to  $f(V)$  then as in (20)*

$$\tilde{H}(BX, BY) = BH(X, Y) \quad (29)$$

*Proof.* From (20) we get

$$\tilde{H}(BX, BY) = \tilde{N}(BX, BY) - \tilde{N}(\tilde{m}BX, BY) - \tilde{N}(BX, \tilde{m}BY) + \tilde{N}(\tilde{m}BX, \tilde{m}BY) \quad (30)$$

Using (22) (a) and (11) in (30) we get (29). □

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