



Discrete Heat Flow Controlled by Alpha-Beta Delay Q-Difference Equations

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Abstract: Partial q-difference equation have extended applications in q-heat equations. Having introduced the Fibonacci difference equation in the partial section by using Fibonacci difference operator with shift values, a model for heat transfer in the rod is found having recourse to Fourier law of cooling, an involved study is carried out to evaluate that movement of heat and thus numerous are postulated. The result obtained are validated by MATLAB.

MSC: 39A70, 39A10, 47B39, 80A20.

Keywords: Partial Difference Equation, Partial Difference Operator and Delay Heat Equation.

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Accepted on: 13th April 2018

1. Introduction

The theory of Δ_α , using the definition $\Delta_\alpha u(k) = u(k+1) - \alpha u(k)$ was introduced by Jerzy Popenda [1, 6] in 1984. Fractional difference operators are established by Miller and Rose in 1989 ([3, 4]). The extension of Δ_α was introduced by M.M.S.Manuel [7, 8] in 2011. The q -difference operator obtained by the authors [5] in 2011 and its extended with the variable coefficients is founded in [5]. Here, we extend the operator Δ_q to a partial q -difference operator. Consider the variable $k = (k_1, k_2, \dots, k_n)$, n-tuple shift factors $q = (q_1, q_2, \dots, q_n) \neq 0$, not all $q_i \neq 1$, $kq = (k_1 q_1, k_2 q_2, \dots, k_n q_n)$ and a real valued function $v(k)$ defined on R^n . The beta q -difference operator on $v(k)$ is defined as

$$\Delta_{\beta(q)} v(k) = v(kq) - \beta v(k). \quad (1)$$

When $q = (1, q_2)$, the beta q -inverse principle with respect to $\Delta_{\beta(1, q_2)}$ is given by

$$v(k_1, k_2) - \beta^m v(k_1, \frac{k_2}{q_2^m}) = \sum_{r=1}^m \beta^{r-1} u(k_1, \frac{k_2}{q_2^{(r+1)}}), \quad (2)$$

where $v(k_1, k_2) = \Delta_{\beta(q_1, q_2)}^{-1} u(k_1, k_2)$ [2]. Using (2), we arrive several type solutions of heat equation for a long rod with delay factor.

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2. Delay q -heat Equation of a Long Rod when γ is Constant

Let us take a long rod and assuming $v(k_1, k_2)$ be the temperature at the position k_1 and its time k_2 of the rod. Let γ be the positive dissemination rate constant of rod. By Fourier's cooling law, the discrete alpha-beta delay q-heat equation of rod is

$$v(k_1, k_2 q_2) - \beta v(k_1, k_2) = \gamma \left[v\left(\frac{k_1}{q_1}, \frac{k_2}{\sigma}\right) - \alpha v\left(k_1, \frac{k_2}{\sigma}\right) + v\left(k_1 q_1, \frac{k_2}{\sigma}\right) - \alpha v\left(k_1, \frac{k_2}{\sigma}\right) \right]. \quad (3)$$

Then the discrete heat equation (3) with delay can be expressed as

$$\beta_{(1, q_2 \pm)} \Delta v(k_1, k_2) = \gamma \Delta_{\alpha(q_1 \pm, 1)} v\left(k_1, \frac{k_2}{\sigma}\right). \quad (4)$$

Our main aim is to analyze the possible solutions of the q-heat equation (4).

Theorem 2.1. *Let us take an integer $m > 0$, and a number $q_2 > 0$ which is real such that $v(k_1, \frac{k_2}{q_2^m})$ and $\Delta_{\alpha(q_1 \pm, 1)} v(k_1, \frac{k_2}{\sigma}) = u_{\alpha(q_1 \pm, 1)}(k_1, \frac{k_2}{\sigma})$ are given then (4) has a summation solution as*

$$v(k_1, k_2) = \alpha^m v\left(k_1, \frac{k_2}{q_2^m}\right) + \gamma \sum_{r=1}^m \alpha^r u_{\alpha(q_1 \pm, 1)}\left(k_1, \frac{k_2}{q_2^r \sigma}\right). \quad (5)$$

Proof. Taking $\Delta_{\alpha(q_1 \pm, 1)} v(k_1, \frac{k_2}{\sigma}) = u_{\alpha(q_1 \pm, 1)}(k_1, \frac{k_2}{\sigma})$ in (4) gives

$$v(k_1, k_2) = \gamma \Delta_{\beta(1, q_2)}^{-1} u_{\alpha(q_1 \pm, 1)}\left(k_1, \frac{k_2}{\sigma}\right). \quad (6)$$

The proof follows by applying inverse principle in (6). \square

Theorem 2.2. *When $\beta > 0$, m is a positive integer and by denoting $v(k_1 q_1^\pm, *) = v(k_1 q_1, *) + v(\frac{k_1}{q_1}, *)$ and $v(*, k_2 q_2^\pm) = v(*, k_2 q_2) + v(*, \frac{k_2}{q_1})$, we get the following results.*

$$(a). \quad v(k_1, k_2) = \frac{1}{\beta^m} v(k_1, k_2 q_2^m) - \sum_{i=1}^m \frac{\gamma}{\beta^i} \left[v\left(k_1 q_1^\pm, \frac{k_2 q_2^{i-1}}{\sigma}\right) - 2\alpha v\left(k_1, \frac{k_2 q_2^{i-1}}{\sigma}\right) \right], \quad (7)$$

$$(b). \quad v(k_1, k_2) = \beta^m v\left(k_1, \frac{k_2}{q_2^m}\right) + \sum_{i=1}^m \beta^{i-1} \gamma \left[v\left(k_1 q_1^\pm, \frac{k_2}{q_2^i \sigma}\right) - 2\alpha v\left(k_1, \frac{k_2}{q_2^i \sigma}\right) \right], \quad (8)$$

$$(c). \quad v(k_1, k_2) = \frac{1}{\gamma^m} v\left(\frac{k_1}{q_1^m}, k_2 q_2^m \sigma^m\right) - \sum_{i=1}^m \frac{\beta}{\gamma^i} v\left(\frac{k_1}{q_1^i}, k_2 q_2^{i-1} \sigma^i\right) \\ - \sum_{i=1}^m \frac{1}{\gamma^{i-1}} v\left(\frac{k_1}{q_1^{i+1}}, k_2 q_2^{i-1} \sigma^{i-1}\right) - \sum_{i=1}^m \frac{2\alpha}{\gamma^{i-1}} v\left(\frac{k_1}{q_1^i}, k_2 q_2^{i-1} \sigma^{i-1}\right), \quad (9)$$

$$(d). \quad v(k_1, k_2) = \frac{1}{\gamma^m} v(k_1 q_1^m, k_2 q_2^m \sigma^m) - \sum_{i=1}^m \frac{\beta}{\gamma^i} v\left(k_1 q_1^i, k_2 q_2^{i-1} \sigma^i\right) \\ - \sum_{i=1}^m \frac{1}{\gamma^{i-1}} v\left(k_1 q_1^{i+1}, k_2 q_2^{i-1} \sigma^{i-1}\right) - \sum_{i=1}^m \frac{2\alpha}{\gamma^{i-1}} v\left(k_1 q_1^i, k_2 q_2^{i-1} \sigma^{i-1}\right). \quad (10)$$

Proof. (a). We have

$$v(k_1, k_2) = \frac{1}{\beta} v(k_1, k_2 q_2) - \frac{\gamma}{\beta} \left[v(k_1 q_1^\pm, \frac{k_2}{\sigma}) - 2\alpha v(k_1, \frac{k_2}{\sigma}) \right] \quad (11)$$

Replacing k_2 by $k_2 q_2, k_2 q_2^2, \dots, k_2 q_2^m$ in (11).

(b). Directly derives the equation

$$v(k_1, k_2) = \beta v(k_1, \frac{k_2}{q_2}) - \gamma \left[v(k_1 q_1^\pm, \frac{k_2}{q_2 \sigma}) - 2\alpha v(k_1, \frac{k_2}{q_2 \sigma}) \right]. \quad (12)$$

By changing k_2 by $\frac{k_2}{q_2}, \frac{k_2}{q_2^2}, \dots, \frac{k_2}{q_2^m}$ repeatedly, we get the result (8).

(c). (4) yeilds $v(k_1, k_2) = \frac{1}{\gamma} v(\frac{k_1}{q_1}, k_2 q_2 \sigma) - \frac{\beta}{\gamma} v(\frac{k_1}{q_1}, \sigma k_2) - v(\frac{k_1}{q_1^2}, k_2) + 2\alpha v(\frac{k_1}{q_1}, k_2)$. When replacing k_1 by $\frac{k_1}{q_1}, \frac{k_1}{q_1^2}, \dots, \frac{k_1}{q_1^m}$ and k_2 by $k_2 q_2 \sigma, k_2 q_2^2 \sigma^2, \dots, k_2 q_2^m \sigma^m$ repeatedly in the above relation we obtained (9).

(d). The proof of (10) follows by replacing k_1 by $k_1 q_1, k_1 q_1^2, \dots, k_1 q_1^m k_2$ by $k_2 q_2 \sigma, k_2 q_2^2 \sigma^2, \dots, k_2 q_2^m \sigma^m$ repeatedly in $v(k_1, k_2) = \frac{1}{\gamma} v(k_1 q_1, k_2 q_2 \sigma) - \frac{\beta}{\gamma} v(k_1 q_1, \sigma k_2) - v(k_1 q_1^2, k_2) + 2\alpha v(k_1 q_1, k_2)$. \square

Example 2.3. Suppose that $v(k_1, k_2) = k_1 k_2$ is a exact solution of (4), $v(k_1, k_2) = \gamma \left[\Delta_{(q_1, 1)} k_1 k_2 + \Delta_{(\frac{1}{q_1}, 1)} k_1 k_2 \right]$ yields $k_1 k_2 q_2 - \beta k_1 k_2 = \gamma [k_1 q_1 k_2 + \frac{k_1}{q_1} k_2 - 2k_1 k_2]$. Canceling $k_1 k_2$ on the both sides derives $\gamma = \frac{q_2 - \beta}{\frac{q_1}{\sigma} + \frac{1}{q_1 \sigma} - \frac{2\alpha}{\sigma}}$. For numerical verification, we give the MATLAB coding for (a) by taking $k_1 = q_1 = 4, k_2 = q_2 = 5, \beta = \sigma = 3, \alpha = 2, m = 20, 4.*5 = ((1./(3). \wedge 20). * (20. * (5. \wedge 20))) - symsum((24./((3. \wedge i)). * ((16.* (5.* (5. \wedge (i-1)))./3) + (1.* (5.* (5. \wedge (i-1)))./3) - (4.* (20.* ((5. \wedge (i-1))./3)))), i, 1, 20)$.

3. Delay q -heat Equation for Thin Plate when γ is Constant

Let $v(k_1, k_2, k_3)$ be the temperature of a thin plate at position (k_1, k_2) and time k_3 . The proportional amount of heat flows from left to right at $k = (k_1, k_2, k_3)$ is $\Delta_{(\frac{1}{q_1}, 1, 1)} v(k)$, right to left $\Delta_{(q_1, 1, 1)} v(k)$, top to bottom $\Delta_{(1, q_2, 1)} v(k)$ and bottom to top $\Delta_{(1, \frac{1}{q_2}, 1)} v(k)$. By Fourier law of cooling and denoting $\Delta_{(q_1 q_2)^\pm} = \Delta_{(q_1, 1, 1)} + \Delta_{(\frac{1}{q_1}, 1, 1)} + \Delta_{(1, q_2, 1)} + \Delta_{(1, \frac{1}{q_2}, 1)}$ the heat equation for the plate is

$$\Delta_{\beta(1, 1, q_3)} v(k_1, k_2, k_3) = \gamma \Delta_{\alpha(q_1, q_2)^\pm} v(k_1, k_2, \frac{k_3}{\sigma}) \quad (13)$$

Theorem 3.1. Let $m > 0$ and $q_3 > 0$ such that $v(k_1, k_2, \frac{k_3}{q_3^m})$ and the partial differences $\Delta_{\alpha(q_1^\pm, 1)} v(k_1, k_2, \frac{k_3}{\sigma}) = u_{(q_1^\pm, 1)}(k_1, k_2, \frac{k_3}{\sigma})$ are known then we have

$$v(k) = \alpha^m v(k_1, k_2, \frac{k_3}{q_3^m}) + \gamma \sum_{r=1}^m \alpha^r u_{\alpha(q_1^\pm, 1)}(k_1, k_2, \frac{k_3}{\sigma q_3^r}). \quad (14)$$

Proof. Taking $\Delta_{\alpha(q_1^\pm, 1)} v(\frac{k}{\sigma}) = u_{\alpha(q_1^\pm, 1)}(\frac{k}{\sigma})$ in (13), we arrive

$$v(k) = \gamma \Delta_{\beta(1, 1, q_3)}^{-1} u_{\alpha(q_1^\pm, 1)} \left(\frac{k}{\sigma} \right). \quad (15)$$

By using the inverse principle of $\Delta_{\beta(q_3)}^{-1}$ in (15) we obtain (14). \square

Consider the following notation which will be used in Theorem 3.2, $v(k_{(1,2)} q_{(1,2)}, *)^\pm = v(k_1 q_1^\pm, k_2, *) + v(k_1, k_2 q_2^\pm, *)$ and also $v(k_{(2,3)} q_{(2,3)}, *)^\pm = v(*, k_2 q_2^\pm, k_3) + v(*, k_2, k_3 q_3^\pm)$.

Theorem 3.2. Assuming (13), then we have the following results

$$(a). \quad v(k_1, k_2, k_3) = \frac{1}{\beta^m} v(k_1, k_2, k_3 q_3^m) - \sum_{i=1}^m \frac{\gamma}{\beta^i} [v(k_1 q_1^\pm, k_2, \frac{k_3 q_3^{i-1}}{\sigma}) + v(k_1, k_2 q_2^\pm, \frac{k_3 q_3^{i-1}}{\sigma})] - 4\alpha v(k_1, k_2, \frac{k_3 q_3^{i-1}}{\sigma}), \quad (16)$$

$$(b). \quad v(k_1, k_2, k_3) = \beta^m v(k_1, k_2, \frac{k_3}{q_3^m}) + \sum_{i=1}^m \beta^{i-1} \gamma [v(k_1 q_1^\pm, k_2, \frac{k_3}{q_3^i \sigma}) + v(k_1, k_2 q_2^\pm, \frac{k_3}{q_3^i \sigma})] - 4\alpha v(k_1, k_2, \frac{k_3}{q_3^i \sigma}), \quad (17)$$

$$(c). \quad v(k_1, k_2, k_3) = \frac{1}{\gamma^m} v(\frac{k_1}{q_1^m}, k_2, k_3 q_3^m \sigma^m) - \sum_{i=1}^m \frac{\beta}{\gamma^i} v(\frac{k_1}{q_1^i}, k_2, k_3 q_3^{i-1} \sigma^i) - \sum_{i=1}^m \frac{1}{\gamma^{i-1}} [v(\frac{k_1}{q_1^{i+1}}, k_2, k_3 q_3^{i-1} \sigma^{i-1}) + v(\frac{k_1}{q_1^i}, k_2 q_2^\pm, k_3 q_3^{i-1} \sigma^{i-1})] - \sum_{i=1}^m \frac{4\alpha}{\gamma^{i-1}} v(\frac{k_1}{q_1^i}, k_2, k_3 q_3^{i-1} \sigma^{i-1}), \quad (18)$$

$$(d). \quad v(k_1, k_2, k_3) = \frac{1}{\gamma^m} v(k_1 q_1^m, k_2, k_3 q_3^m \sigma^m) - \sum_{i=1}^m \frac{\beta}{\gamma^i} v(k_1 q_1^i, k_2, k_3 q_3^{i-1} \sigma^i) - \sum_{i=1}^m \frac{1}{\gamma^{i-1}} [v(k_1 q_1^{i+1}, k_2, k_3 q_3^{i-1} \sigma^{i-1}) + v(k_1 q_1^i, k_2 q_2^\pm, k_3 q_3^{i-1} \sigma^{i-1})] - \sum_{i=1}^m \frac{4\alpha}{\gamma^{i-1}} v(k_1 q_1^i, k_2, k_3 q_3^{i-1} \sigma^{i-1}). \quad (19)$$

Proof. The proof and verification are as similar as in the case of long rod. \square

4. Delay q -heat Equation of Medium when γ is Constant

By the Fourier law of cooling, the heat equation for medium in \Re^3 is

$$\beta_{(q_4, q_5)} \Delta v(k) = \gamma \Delta_{\alpha(q_1, q_2, q_3)^\pm} v\left(\frac{k}{\sigma}\right), \quad (20)$$

where $\Delta_{(q_1, q_2, q_3)^\pm} = \Delta_{(q_1)} + \Delta_{(\frac{1}{q_1})} + \Delta_{(q_2)} + \Delta_{(\frac{1}{q_2})} + \Delta_{(q_3)} + \Delta_{(\frac{1}{q_3})}$ and $k = (k_1, k_2, k_3, k_4, k_5)$.

Theorem 4.1. Assume that the function $\alpha_{(q_1, q_2, q_3)^\pm} v\left(\frac{k}{\sigma}\right) = \alpha_{(q_1, q_2, q_3)^\pm} u\left(\frac{k}{\sigma}\right)$ is known. Then (20) satisfies the relation

$$v(k) = v(k_1, k_2, k_3, \frac{k_4}{q_4^m}, \frac{k_5}{q_5^m}) + \gamma \sum_{r=1}^m \alpha_{(q_1, q_2, q_3)^\pm} (k_1, k_2, k_3, \frac{k_4}{q_4^r \sigma}, \frac{k_5}{q_5^r \sigma}). \quad (21)$$

Proof. Taking $\alpha_{(q_1, q_2, q_3)^\pm} v\left(\frac{k}{\sigma}\right) = \alpha_{(q_1, q_2, q_3)^\pm} u\left(\frac{k}{\sigma}\right)$ in (20), we get

$$v(k) = \gamma \Delta_{(q_4, q_5)}^{-1} \alpha_{(q_1, q_2, q_3)^\pm} u\left(\frac{k}{\sigma}\right). \quad (22)$$

Then using the inverse principle in (22) we get (21). \square

In the below theorem, we use the following notations:

$$\begin{aligned} v(k_{(1,2,3)} q_{(1,2,3)}^\pm, *, *) &= v(k_1 q_1, k_2, k_3, *, *) + v(\frac{k_1}{q_1}, k_2, k_3, *, *) + v(k_1, k_2 q_2, k_3, *, *) + v(k_1, \frac{k_2}{q_2}, k_3, *, *) \\ &\quad + v(k_1, k_2, k_3 q_3, *, *) + v(k_1, k_2, \frac{k_3}{q_3}, *, *). \\ v(*, k_{(2,3)} q_{(2,3)}^\pm, *, *) &= v(*, k_2 q_2, k_3, *, *) + v(*, \frac{k_2}{q_2}, k_3, *, *) + v(*, k_2, k_3 q_3, *, *) + v(*, k_2, \frac{k_3}{q_3}, *, *). \end{aligned}$$

Theorem 4.2. If $v(k)$ is a solution of the equation (20) and $m > 0$ and $k = (k_1, k_2, k_3, k_4, k_5)$ then the following relations are equivalent:

$$(a). \quad v(k, k_4, k_5) = \frac{1}{\beta^m} v(k, k_4 q_4^m, k_5 q_5^m) - \sum_{i=1}^m \frac{\gamma}{\beta^i} \left[v(kq_1^\pm, \frac{k_4 q_4^{i-1}}{\sigma}, \frac{k_5 q_5^{i-1}}{\sigma}) + v(kq_2^\pm, \frac{k_4 q_4^{i-1}}{\sigma}, \frac{k_5 q_5^{i-1}}{\sigma}) + v(kq_3^\pm, \frac{k_4 q_4^{i-1}}{\sigma}, \frac{k_5 q_5^{i-1}}{\sigma}) - 6\alpha v(k, \frac{k_4 q_4^{i-1}}{\sigma}, \frac{k_5 q_5^{i-1}}{\sigma}) \right], \quad (23)$$

$$(b). \quad v(k, k_4, k_5) = \beta^m v(k, \frac{k_4}{q_4^m}, \frac{k_5}{q_5^m}) + \sum_{i=1}^m \beta^{i-1} \gamma \left[v(kq_1^\pm, \frac{k_4}{q_4^i \sigma}, \frac{k_5}{q_5^i \sigma}) + v(kq_2^\pm, \frac{k_4}{q_4^i \sigma}, \frac{k_5}{q_5^i \sigma}) + v(kq_3^\pm, \frac{k_4}{q_4^i \sigma}, \frac{k_5}{q_5^i \sigma}) - 6\alpha v(k, \frac{k_4}{q_4^i \sigma}, \frac{k_5}{q_5^i \sigma}) \right], \quad (24)$$

$$(c). \quad v(k, k_4, k_5) = \frac{1}{\gamma^m} v(\frac{k}{q_1^m}, k_4 q_4^m \sigma^m, k_5 q_5^m \sigma^m) - \sum_{i=1}^m \frac{\beta}{\gamma^i} v(\frac{k}{q_1^i}, k_4 q_4^{i-1} \sigma^i, k_5 q_5^{i-1} \sigma^i) - \sum_{i=1}^m \frac{1}{\gamma^{i-1}} \left[v(\frac{k}{q_1^{i+1}}, k_4 q_4^{i-1} \sigma^{i-1}, k_5 q_5^{i-1} \sigma^{i-1}) + v(\frac{kq_1^\pm}{q_1^i}, k_4 q_4^{i-1} \sigma^{i-1}, k_5 q_5^{i-1} \sigma^{i-1}) \right] - \sum_{i=1}^m \frac{6\alpha}{\gamma^{i-1}} v(\frac{k}{q_1^i}, k_4 q_4^{i-1} \sigma^{i-1}, k_5 q_5^{i-1} \sigma^{i-1}), \quad (25)$$

$$(d). \quad v(k, k_4, k_5) = \frac{1}{\gamma^m} v(kq_1^m, k_4 q_4^m \sigma^m, k_5 q_5^m \sigma^m) - \sum_{i=1}^m \frac{\beta}{\gamma^i} v(kq_1^i, k_4 q_4^{i-1} \sigma^i, k_5 q_5^{i-1} \sigma^i) - \sum_{i=1}^m \frac{1}{\gamma^{i-1}} \left[v(kq_1^{i+1}, k_4 q_4^{i-1} \sigma^{i-1}, k_5 q_5^{i-1} \sigma^{i-1}) + v(kq_2^\pm q_1^i, k_4 q_4^{i-1} \sigma^{i-1}, k_5 q_5^{i-1} \sigma^{i-1}) \right] - \sum_{i=1}^m \frac{6\alpha}{\gamma^{i-1}} v(kq_1^i, k_4 q_4^{i-1} \sigma^{i-1}, k_5 q_5^{i-1} \sigma^{i-1}), \quad (26)$$

Proof. The proof and verification are as similar as Theorem 3.2. \square

5. Conclusion

The newly introduced partial q-difference operator with its corresponding equations has many applications in the field of finite difference methods and q-heat equations. The nature of propagation of heat through the rod is studied using partial Fibonacci difference operator. The results obtained above gives us the tool to predict the temperature and also gives us the possibility to determine the nature of the rod under study for better transmission.

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