

Best Proximity Point Theorems for d -Rational Cyclic Contractions in Dislocated Metric Spaces

Ajay Kumar Sharma¹, Manjari Dewangan², M. P. Goswami^{3,*}

¹*Department of Mathematics, Seth Phoolchand Agrawal Smriti Mahavidyalaya, Nawapara, Raipur, Chhattisgarh, India*

²*S.o.S. in Mathematics, Pt. Ravishankar Shukla University, Raipur, Chhattisgarh, India*

³*Department of Mathematics, Kalyan PG College, Bhilai Nagar, Chhattisgarh, India*

Abstract

In this work, we define d -rational cyclic contraction in the setting of dislocated metric space. Some existence and convergence results for best proximity points have been demonstrated. Further, illustrative examples are provided in the support of results proved.

Keywords: Dislocated metric space; Best proximity point; Cyclic contraction.

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1. Introduction

The study of fixed point theory provides essential tools for analyzing nonlinear equations such as $Tx = x$, particularly when T is a self-mapping defined on a subset of a normed linear space or a metric space. The Banach contraction principle [4], established in 1922, is one of the classical results in fixed point theory.

When considering a non-self mapping $T : A \rightarrow B$, where A and B are nonempty subsets of a metric space X , the fixed point equation $Tx = x$ does not necessarily have a solution. In such situations, one seeks an element $x \in A$ that is, in some sense, closest to its image $Tx \in B$. This leads to the development of the concepts of best approximation and best proximity points. In 1969, Ky Fan [9] established the famous best approximation theorem in this direction. He proved that if A is a nonempty compact convex subset of a Hausdorff locally convex topological vector space X , and $T : A \rightarrow B$ is a continuous single-valued mapping, then there exists a point $x \in A$ such that $d(x, Tx) = d(Tx, A)$. This result initiated a broad area of research, and many generalizations and extensions of Fan's theorem have been developed by numerous researchers (one may refer [24,27,29–31]).

On the other hand, in the case of best proximity point problem, the objective is to find an element x such that $d(A, B) = \inf\{d(x, y) : x \in A, y \in B\}$. It is evident that for any point $x \in A$, we have

*Corresponding author (mayurpuri89@gmail.com)

$d(x, Tx) \geq d(A, B)$. A point $x \in A$ is called a best proximity point for the mapping T if $d(A, B) = d(x, Tx)$. In other words, if x is the best proximity point, then the function $d(x, Tx)$ attains its global minimum at x , and this minimum value equals $d(A, B)$. Furthermore, when $d(A, B) = 0$, then the best proximity point coincides with a fixed point of the mapping T . In 2006, Eldred and Veeramani [8] introduced the concept of cyclic contraction as follows:

Definition 1.1 ([8]). *Let A and B be two nonempty subsets of a metric space X . A mapping $T : A \cup B \rightarrow A \cup B$ is called a cyclic contraction if it is cyclic and there exists $\alpha \in (0, 1)$ such that*

$$d(Tx, Ty) \leq \alpha d(x, y) + (1 - \alpha)d(A, B) \quad \text{for all } x \in A, y \in B.$$

They provided sufficient conditions for the existence of a best proximity point for cyclic contractions in uniformly convex Banach spaces. Further, this result has been extended and generalized by various authors (see [2,5,16,23,26,28]).

In 1975, Khan [18] generalized Banach's contraction principle by employing a symmetric rational expression. Further, in 1977, Jaggi [15] established a fixed point theorem involving rational expressions, which initiated further studies in this direction. Later, in 2013, Yadav et al. [33] introduced the concept of rational cyclic contraction and utilized it to prove best proximity point theorems in complete metric spaces.

Subsequently, numerous extensions and generalizations of rational type contractions have been proposed in [6,7,32], and other works. Over the years, researchers have explored various generalizations of metric spaces by relaxing some of the classical axioms. One such structure is the dislocated metric space, which allows meaningful analysis even without the strict requirement of the symmetry property being bidirectional. The notion traces back to Matthews in 1986 [22] through the concept of metric domains, later refined as domain theory by Abramsky and Jung [1]. The term dislocated metric space was formally introduced in 2000 by Hitzler and Seda [14], who also extended Banach's contraction principle to this setting [13]. Subsequent contributions by Amini-Harandi [12] under the name metric-like space, as well as studies by George et al. [10], Purdhvi [25], who extended fixed point within this framework. Further developments have been made by authors such as [3,11,20,21] and others, which have significantly enriched the theory.

Inspired by these literatures, the present work defines a d -rational cyclic contraction in dislocated metric spaces and establishes best proximity point theorems along with supporting examples.

2. Preliminaries

In this section, we recall basic definitions and known results related to dislocated metric spaces, which form the foundation for the main results presented in this paper.

Definition 2.1 ([14]). *Let X be a nonempty set. A mapping $d : X \times X \rightarrow [0, \infty)$ is a dislocated metric if, for all*

$x, y, z \in X$, the following properties hold:

1. $d(x, y) \geq 0$
2. $d(x, y) = 0 \Rightarrow x = y$
3. $d(x, y) = d(y, x)$
4. $d(x, y) \leq d(x, z) + d(z, y)$.

A pair (X, d) satisfying these conditions is called a dislocated metric space, also known as a d -metric space.

Definition 2.2 ([19]). Let A and B be nonempty subsets of a metric space (X, d) . A map $T : A \cup B \rightarrow A \cup B$ is said to be cyclic map if $T(A) \subseteq B$ and $T(B) \subseteq A$.

Definition 2.3 ([10]). Let A and B be two nonempty closed subsets of a dislocated metric space (X, d) . A mapping $T : A \cup B \rightarrow A \cup B$ is called a d -cyclic contraction if there exists $\alpha \in (0, \frac{1}{2})$ such that $d(Tx, Ty) \leq \alpha d(x, y)$ for all $x \in A$ and $y \in B$.

Definition 2.4 ([14]). A sequence $\{x_n\}$ in a dislocated metric space (X, d) is said to be Cauchy sequence if, for every $\epsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that for all $m, n \geq n_0$, $d(x_m, x_n) < \epsilon$.

Definition 2.5 ([14]). A sequence $\{x_n\}$ in a dislocated metric space (X, d) is said to be d -convergent to a point $x \in X$ if, for every $\epsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that for all $n \geq n_0$, $d(x_n, x) < \epsilon$. In this case, we say that $\{x_n\}$ d -converges to a point $x \in X$ and written as $\{x_n\} \rightarrow x$.

Definition 2.6 ([14]). A dislocated metric space (X, d) is said to be d -complete if every Cauchy sequence in X is d -convergent, i.e, it converges to a point in X with respect to the d -metric.

Lemma 2.7 ([17]). Let (X, d) be a dislocated metric space, and $\{x_n\}$ be a sequence in X that converges to x with $d(x, x) = 0$. Then $\lim_{n \rightarrow \infty} d(x_n, y) = d(x, y)$ for all $y \in X$.

3. Main Results

In this section, we introduce the concept of a d -rational cyclic contraction and establish existence and convergence results for best proximity points.

Definition 3.1. Let A and B be nonempty subsets of a dislocated metric space (X, d) . A mapping $T : A \cup B \rightarrow A \cup B$ is said to be a d -rational cyclic contraction if there exists $\alpha, \beta, \gamma, \delta > 0$ satisfying $0 < \alpha + \beta + 4\gamma + \delta < 1$, such that

$$d(Tx, Ty) \leq \alpha d(x, y) + \beta \frac{d(x, Tx)d(y, Ty)}{d(x, y)} + \gamma \frac{d(x, Tx)d(x, Ty) + d(y, Ty)d(y, Tx)}{d(x, y)} + \delta d(A, B) \quad (1)$$

for all $x \in A$ and $y \in B$.

Theorem 3.2. Let A and B be two nonempty closed subsets of a complete dislocated metric space (X, d) . Suppose a mapping $T : A \cup B \rightarrow A \cup B$ is a d -rational cyclic contraction in X . For $x_0 \in A \cup B$ we define $x_{n+1} = Tx_n$ for all $n \geq 0$. Then there exists a sequence $\{x_n\}$ in X such that

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = d(A, B).$$

Proof. Let $x_0 \in A \cup B$ and consider an iterative sequence $\{x_n\}$ in X defined by $x_{n+1} = Tx_n$ for all $n \in \mathbb{N}$. Since T is a d -rational cyclic contraction in X , by inequality (1), we have

$$\begin{aligned} d(x_n, x_{n+1}) &= d(Tx_{n-1}, Tx_n) \\ &\leq \alpha d(x_{n-1}, x_n) + \beta \frac{d(x_{n-1}, Tx_{n-1})d(x_n, Tx_n)}{d(x_{n-1}, x_n)} \\ &\quad + \gamma \frac{d(x_{n-1}, Tx_{n-1})d(x_{n-1}, Tx_n) + d(x_n, Tx_n)d(x_n, Tx_{n-1})}{d(x_{n-1}, x_n)} + \delta d(A, B) \\ &\leq \alpha d(x_{n-1}, x_n) + \beta \frac{d(x_{n-1}, x_n)d(x_n, x_{n+1})}{d(x_{n-1}, x_n)} \\ &\quad + \gamma \frac{d(x_{n-1}, x_n)d(x_{n-1}, x_{n+1}) + d(x_n, x_{n+1})d(x_n, x_n)}{d(x_{n-1}, x_n)} + \delta d(A, B) \\ &\leq \alpha d(x_{n-1}, x_n) + \beta d(x_n, x_{n+1}) \\ &\quad + \gamma \frac{d(x_{n-1}, x_n)d(x_{n-1}, x_{n+1}) + d(x_n, x_{n+1})[d(x_n, x_{n-1}) + d(x_{n-1}, x_n)]}{d(x_{n-1}, x_n)} + \delta d(A, B) \\ &\leq \alpha d(x_{n-1}, x_n) + \beta d(x_n, x_{n+1}) \\ &\quad + \gamma \frac{(x_{n-1}, x_n)[d(x_{n-1}, x_{n+1}) + 2d(x_n, x_{n+1})]}{d(x_{n-1}, x_n)} + \delta d(A, B) \\ &\leq \alpha d(x_{n-1}, x_n) + \beta d(x_n, x_{n+1}) + \gamma[d(x_{n-1}, x_n) + 3d(x_n, x_{n+1})] + \delta d(A, B). \end{aligned}$$

It follows that

$$d(x_n, x_{n+1}) \leq (\alpha + \gamma)d(x_{n-1}, x_n) + (\beta + 3\gamma)d(x_n, x_{n+1}) + \delta d(A, B),$$

and hence

$$(1 - \beta - 3\gamma)d(x_n, x_{n+1}) \leq (\alpha + \gamma)d(x_{n-1}, x_n) + \delta d(A, B).$$

Thus

$$d(x_n, x_{n+1}) \leq \frac{(\alpha + \gamma)}{1 - \beta - 3\gamma}d(x_{n-1}, x_n) + \frac{\delta}{1 - \beta - 3\gamma}d(A, B),$$

which implies that,

$$d(x_n, x_{n+1}) \leq kd(x_{n-1}, x_n) + (1 - k)d(A, B),$$

where $\frac{(\alpha+\gamma+\delta)}{1-\beta-3\gamma} < 1$ and hence $k = \frac{(\alpha+\gamma)}{1-\beta-3\gamma} < 1$.

Repeating this process continuously, we get

$$\begin{aligned} d(x_n, x_{n+1}) &\leq kd(x_{n-1}, x_n) + (1 - k)d(A, B) \\ &\leq k^2d(x_{n-2}, x_{n-1}) + (1 - k^2)d(A, B) \\ &\vdots \\ &\leq k^nd(x_0, x_1) + (1 - k^n)d(A, B). \end{aligned}$$

Since $k \in (0, 1)$, we have $\lim_{n \rightarrow \infty} k^n = 0$, which implies

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = d(A, B).$$

This completes the proof. □

Theorem 3.3. *Let A and B be nonempty closed subsets of a dislocated metric space (X, d) . Suppose $T : A \cup B \rightarrow A \cup B$ is a d -rational cyclic contraction in X . Let $x_0 \in A \cup B$ and define the sequence $\{x_n\}$ by $x_{n+1} = Tx_n$. If $\{x_{2n}\}$ is a convergent subsequence of $\{x_n\}$ that converges to x in A with $d(x, x) = 0$. Then the sequence $\{x_n\}$ is bounded.*

Proof. By Theorem 3.2, we have

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = d(A, B).$$

Suppose $\{x_{2n}\}$ is a convergent subsequence of $\{x_n\}$ that converges to $x \in A$ with $d(x, x) = 0$. Since T is a d -rational cyclic contraction in X , from inequality (1) and the lemma 2.7, we have

$$\begin{aligned} d(x_{2n}, Tx) &= d(Tx_{2n-1}, Tx) \\ &\leq \alpha d(x_{2n-1}, x) + \beta \frac{d(x_{2n-1}, Tx_{2n-1})d(x, Tx)}{d(x_{2n-1}, x)} \\ &\quad + \gamma \frac{d(x_{2n-1}, Tx_{2n-1})d(x_{2n-1}, Tx) + d(x, Tx)d(x, Tx_{2n-1})}{d(x_{2n-1}, x)} + \delta d(A, B) \\ &\leq \alpha d(x_{2n-1}, x) + \beta \frac{d(x_{2n-1}, x_{2n})d(x, Tx)}{d(x_{2n-1}, x)} \\ &\quad + \gamma \frac{d(x_{2n-1}, x_{2n})d(x_{2n-1}, Tx) + d(x, Tx)d(x, x_{2n})}{d(x_{2n-1}, x)} + \delta d(A, B) \\ &\leq \alpha d(x_{2n-1}, x) + \beta \frac{[d(x_{2n-1}, x) + d(x, x_{2n})]d(x, Tx)}{d(x_{2n-1}, x)} \\ &\quad + \gamma \frac{[d(x_{2n-1}, x) + d(x, x_{2n})]d(x_{2n-1}, Tx) + d(x, Tx)d(x, x_{2n})}{d(x_{2n-1}, x)} + \delta d(A, B) \\ &\leq \alpha d(x_{2n-1}, x) + \beta d(x, Tx) + \gamma d(x_{2n-1}, Tx) + \delta d(A, B) \\ &\leq \alpha [d(x_{2n-1}, x_{2n}) + d(x_{2n}, x)] + \beta [d(x, x_{2n}) + d(x_{2n}, Tx)] \\ &\quad + \gamma [d(x_{2n-1}, x_{2n}) + d(x_{2n}, Tx)] + \delta d(A, B) \end{aligned}$$

$$\leq (\alpha + \gamma)d(x_{2n-1}, x_{2n}) + \beta d(x_{2n}, Tx) + \gamma d(x_{2n}, Tx) + \delta d(A, B).$$

It follows that

$$(1 - \beta - \gamma)d(x_{2n}, Tx) \leq (\alpha + \gamma)d(x_{2n-1}, x_{2n}) + \delta d(A, B).$$

Therefore

$$d(x_{2n}, Tx) \leq \frac{\alpha + \gamma}{(1 - \beta - \gamma)}d(x_{2n-1}, x_{2n}) + \frac{\delta}{(1 - \beta - \gamma)}d(A, B).$$

Let

$$\mu = \frac{\alpha + \gamma}{(1 - \beta - \gamma)}d(x_{2n-1}, x_{2n}) + \frac{\delta}{(1 - \beta - \gamma)}d(A, B).$$

Thus, we have

$$d(x_{2n}, Tx) = \mu,$$

which implies

$$x_{2n} \in \overline{B}(T(x, \mu)) \text{ for all } n \in \mathbb{N}.$$

Now, consider

$$d(x_{2n+1}, Tx) \leq d(x_{2n}, x_{2n+1}) + d(x_{2n}, Tx) \leq L + \mu,$$

for some constant L , which gives

$$x_{2n+1} \in \overline{B}(Tx, \mu + L) \text{ for all } n \in \mathbb{N}.$$

Since

$$x_{2n} \in \overline{B}(Tx, \mu) \subset \overline{B}(Tx, \mu + L) \text{ for all } n \in \mathbb{N},$$

it follows that

$$x_n \in \overline{B}(Tx, \mu + L) \text{ for all } n \in \mathbb{N}.$$

So the sequence $\{x_n\}$ is bounded. This completes the proof. \square

Theorem 3.4. Let A and B be nonempty closed subsets of a dislocated metric space (X, d) . Let $T : A \cup B \rightarrow A \cup B$ is a d -rational cyclic contraction in X , and let $x_0 \in A \cup B$ with the sequence $\{x_n\}$ defined by $x_{n+1} = Tx_n$ for all $n \geq 0$. Then we have the following:

- (i). If $x_0 \in A$ and the subsequence $\{x_{2n_k}\}$ of $\{x_{2n}\}$ converges to $x \in A$ such that $d(x, x) = 0$, then $x \in A$ is a best proximity point of T , that is,

$$d(x, Tx) = d(A, B).$$

- (ii). If $x_0 \in B$ and the subsequence $\{x_{2n_k-1}\}$ of $\{x_{2n-1}\}$ converges to $y \in B$ such that $d(y, y) = 0$, then $y \in B$

is a best proximity point of T , that is,

$$d(y, Ty) = d(A, B).$$

Proof. Suppose $\{x_{2n_k}\}$ is convergent subsequence of the sequence $\{x_{2n}\}$, converging to a point $x \in A$ such that $d(x, x) = 0$. Since T is a d -rational cyclic contraction in X , so by applying lemma 2.7, together with Theorem 3.2, implies

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = d(A, B).$$

By inequality (1), we have

$$\begin{aligned} d(x_{2n_k}, Tx) &= d(Tx_{2n_k-1}, Tx) \\ &\leq \alpha d(x_{2n_k-1}, x) + \beta \frac{d(x_{2n_k-1}, Tx_{2n_k-1})d(x, Tx)}{d(x_{2n_k-1}, x)} \\ &\quad + \gamma \frac{d(x_{2n_k-1}, Tx_{2n_k-1})d(x_{2n_k-1}, Tx) + d(x, Tx)d(x, Tx_{2n_k-1})}{d(x_{2n_k-1}, x)} + \delta d(A, B) \\ &\leq \alpha d(x_{2n_k-1}, x) + \beta \frac{d(x_{2n_k-1}, x_{2n_k})d(x, Tx)}{d(x_{2n_k-1}, x)} \\ &\quad + \gamma \frac{d(x_{2n_k-1}, x_{2n_k})d(x_{2n_k-1}, Tx) + d(x, Tx)d(x, x_{2n_k})}{d(x_{2n_k-1}, x)} + \delta d(A, B) \\ &\leq \alpha d(x_{2n_k-1}, x) + \beta \frac{[d(x_{2n_k-1}, x) + d(x, x_{2n_k})]d(x, Tx)}{d(x_{2n_k-1}, x)} \\ &\quad + \gamma \frac{[d(x_{2n_k-1}, x) + d(x, x_{2n_k})]d(x_{2n_k-1}, Tx) + d(x, Tx)d(x, x_{2n_k})}{d(x_{2n_k-1}, x)} + \delta d(A, B) \\ &\leq \alpha d(x_{2n_k-1}, x) + \beta d(x, Tx) + \gamma d(x_{2n_k-1}, Tx) + \delta d(A, B) \\ &\leq \alpha [d(x_{2n_k-1}, x_{2n_k}) + d(x_{2n_k}, x)] + \beta [d(x, x_{2n_k}) + d(x_{2n_k}, Tx)] \\ &\quad + \gamma [d(x_{2n_k-1}, x_{2n_k}) + d(x_{2n_k}, Tx)] + \delta d(A, B) \\ &\leq (\alpha + \gamma)d(x_{2n_k-1}, x_{2n_k}) + \beta d(x_{2n_k}, Tx) + \gamma d(x_{2n_k}, Tx) + \delta d(A, B) \\ &\leq (\alpha + \gamma)d(x_{2n_k-1}, x_{2n_k}) + \beta d(x_{2n_k}, Tx) + 3\gamma d(x_{2n_k}, Tx) + \delta d(A, B). \end{aligned}$$

It follows that

$$(1 - \beta - 3\gamma)d(x_{2n_k}, Tx) \leq (\alpha + \gamma)d(x_{2n_k-1}, x_{2n_k}) + \delta d(A, B).$$

Hence,

$$\begin{aligned} d(x_{2n_k}, Tx) &\leq \frac{\alpha + \gamma}{(1 - \beta - 3\gamma)}d(x_{2n_k-1}, x_{2n_k}) + \frac{\delta}{(1 - \beta - 3\gamma)}d(A, B). \\ d(x_{2n_k}, Tx) &\leq kd(x_{2n_k-1}, x_{2n_k}) + (1 - k)d(A, B). \end{aligned}$$

where $\frac{(\alpha + \gamma + \delta)}{1 - \beta - 3\gamma} < 1$, and hence $k = \frac{(\alpha + \gamma)}{1 - \beta - 3\gamma} < 1$.

Letting $n \rightarrow \infty$, we conclude that

$$\begin{aligned} d(x, Tx) &\leq kd(A, B) + (1 - k)d(A, B) \\ &\leq d(A, B). \end{aligned}$$

Hence, $d(x, Tx) = d(A, B)$. Therefore, x is the best proximity point of T . In a similar manner, we can prove case (ii). \square

Let us demonstrate the following example.

Example 3.5. Consider $X = \mathbb{R}^+ \cup \{0\}$ equipped with $d(x, y) = x + y$ for all $x, y \in X$. Clearly, (X, d) is a dislocated metric space. Let $A = [0, \frac{1}{2}]$, $B = [\frac{1}{2}, 1]$ and define a mapping $T : A \cup B \rightarrow A \cup B$ by

$$T(x) = \begin{cases} 1, & \text{for } x \in [0, \frac{1}{2}) \\ 0, & \text{for } x \in [\frac{1}{2}, 1]. \end{cases}$$

In this case, we have $d(A, B) = \frac{1}{2}$, $T(A) \subset B$, $T(B) \subset A$. Moreover, for every $x \in A$, $y \in B$, there exists $\alpha, \beta, \gamma, \delta > 0$ such that the cyclic map T satisfies the d -rational cyclic contraction. Also, it is observed that $\frac{1}{2} \in B$ is the best proximity point for T .

Corollary 3.6. Let A and B be two nonempty closed subsets of a complete dislocated metric space (X, d) . Suppose that $T : A \cup B \rightarrow A \cup B$ is a cyclic mapping satisfying

$$d(Tx, Ty) \leq \alpha d(x, y) \quad \text{for all } x \in A, y \in B,$$

where $0 < \alpha < 1$. Then, there is a unique fixed point in $A \cap B$.

Proof. By taking $\beta = \gamma = \delta = 0$ in Theorem 3.2, and following the same argument as in that theorem, the result follows immediately. This result also corresponds to Theorem 3.3 in [10]. \square

Corollary 3.7. Let A and B be two nonempty closed subsets of a complete dislocated metric space (X, d) . Suppose that $T : A \cup B \rightarrow A \cup B$ is a cyclic mapping satisfying

$$d(Tx, Ty) \leq \alpha d(x, y) + (1 - \alpha)d(A, B) \quad \text{for all } x \in A, y \in B,$$

where $0 < \alpha < 1$. Then there is a sequence $\{x_n\}$ such that

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = d(A, B).$$

Proof. By taking $\gamma = \beta = 0$ in Theorem 3.2, and following the same argument as in that theorem, the result follows immediately. \square

Corollary 3.8. Let A and B be two nonempty closed subsets of a complete dislocated metric space (X, d) . Suppose that $T : A \cup B \rightarrow A \cup B$ is a cyclic mapping, and there exists $\alpha, \gamma, \delta > 0$ such that $\alpha + 4\gamma + \delta < 1$, satisfying

$$d(Tx, Ty) \leq \alpha d(x, y) + \gamma \frac{d(x, Tx)d(x, Ty) + d(y, Ty)d(y, Tx)}{d(x, y)} + \delta d(A, B)$$

for all $x \in A, y \in B$. Then there exists a sequence $\{x_n\}$ such that

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = d(A, B).$$

Proof. By taking $\beta = 0$ in Theorem 3.2, and following the same argument as in that theorem, the result follows immediately. \square

Corollary 3.9. Let A and B be two non-empty, closed subsets of a complete dislocated metric space (X, d) . Suppose that $T : A \cup B \rightarrow A \cup B$ is a cyclic mapping, and there exists $\alpha, \beta, \delta > 0$ such that $\alpha + \beta + \delta < 1$, satisfying

$$d(Tx, Ty) \leq \alpha d(x, y) + \beta \frac{d(x, Tx)d(y, Ty)}{d(x, y)} + \delta d(A, B)$$

for all $x \in A, y \in B$. Then there exists a sequence $\{x_n\}$ such that

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = d(A, B).$$

Proof. By taking $\gamma = 0$ in Theorem (3.2) and following the same argument as in that theorem, the result follows immediately. \square

Corollary 3.10. Let A and B be two nonempty closed subsets of a complete dislocated metric space (X, d) . Suppose that $T : A \cup B \rightarrow A \cup B$ is a cyclic mapping, and there exists $\gamma \in (0, \frac{1}{4})$, satisfying

$$d(Tx, Ty) \leq k \frac{d(x, Tx)d(x, Ty) + d(y, Ty)d(y, Tx)}{d(x, y)}$$

for all $x \in A, y \in B$. Then T has a unique fixed point in $A \cap B$.

Proof. By taking $\alpha = \beta = \delta = 0$ in Theorem (3.2) and following the same reasoning as in that theorem, the result follows immediately. \square

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