



# $\check{g}$ -closed and $\check{g}$ -open Maps in Topological Spaces

Research Article

O.Ravi<sup>1\*</sup>, S.Padmasekaran<sup>2</sup>, S.Usharani<sup>3</sup> and I.Rajasekaran<sup>1</sup>

1 Department of Mathematics, P. M. Thevar College, Usilampatti, Madurai District, Tamil Nadu, India.

2 Department of Mathematics, Periyar University, Salem, Tamil Nadu, India.

3 Research Scholar, Periyar University, Salem, Tamil Nadu, India.

**Abstract:** A set  $A$  in a topological space  $(X, \tau)$  is said to be  $\check{g}$ -closed set if  $\text{cl}(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $B$ -open in  $X$ . In this paper, we introduce  $\check{g}$ -closed map from a topological space  $X$  to a topological space  $Y$  as the image of every closed set is  $\check{g}$ -closed, and also we prove that the composition of two  $\check{g}$ -closed maps need not be a  $\check{g}$ -closed map. We also obtain some properties of  $\check{g}$ -closed maps.

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## 1. Introduction

Malghan [8] introduced the concept of generalized closed maps in topological spaces. Devi [5] introduced and studied  $sg$ -closed maps and  $gs$ -closed maps. Recently, Sheik John [16] defined  $\omega$ -closed maps and studied some of their properties. In this paper, we introduce  $\check{g}$ -closed maps,  $\check{g}$ -open maps,  $\check{g}^*$ -closed maps and  $\check{g}^*$ -open maps in topological spaces and obtain certain characterizations of these classes of maps.

## 2. Preliminaries

Throughout this paper,  $(X, \tau)$ ,  $(Y, \sigma)$  and  $(Z, \eta)$  (or  $X$ ,  $Y$  and  $Z$ ) represent topological spaces on which no separation axioms are assumed unless otherwise mentioned. For any subset  $A$  of a space  $(X, \tau)$ , the closure of  $A$ , the interior of  $A$  and the complement of  $A$  are denoted by  $\text{cl}(A)$ ,  $\text{int}(A)$  and  $A^c$  respectively.

We recall the following definitions which are useful in the sequel.

**Definition 2.1.** A subset  $A$  of a space  $(X, \tau)$  is called semi-open set [7] if  $A \subseteq \text{cl}(\text{int}(A))$ . The complement of semi-open set is semi-closed.

The semi-closure [4] of a subset  $A$  of  $X$ , denoted by  $\text{scl}(A)$ , is defined to be the intersection of all semi-closed sets of  $(X, \tau)$  containing  $A$ . It is known that  $\text{scl}(A)$  is a semi-closed set. For any subset  $A$  of an arbitrarily chosen topological space, the semi-interior [4] of  $A$ , denoted by  $\text{sint}(A)$ , is defined to be the union of all semi-open sets of  $(X, \tau)$  contained in  $A$ .

\* E-mail: [siingam@yahoo.com](mailto:siingam@yahoo.com)

**Definition 2.2.** A subset  $A$  of a space  $(X, \tau)$  is called:

- (1). a generalized closed (briefly,  $g$ -closed) set [6] if  $cl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is open in  $X$ . The complement of  $g$ -closed set is called  $g$ -open set;
- (2). a  $\hat{g}$ -closed set [18] (=  $\omega$ -closed set [16]) if  $cl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is semi-open in  $X$ . The complement of  $\hat{g}$ -closed set is called  $\hat{g}$ -open set;
- (3). a semi-generalized closed (briefly,  $sg$ -closed) set [2] if  $scl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is semi-open in  $X$ . The complement of  $sg$ -closed set is called  $sg$ -open set;
- (4). a generalized semi-closed (briefly,  $gs$ -closed) set [1] if  $scl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is open in  $X$ . The complement of  $gs$ -closed set is called  $gs$ -open set;
- (5). a  $\check{g}$ -closed set [10] if  $cl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $sg$ -open in  $X$ . The complement of  $\check{g}$ -closed set is called  $\check{g}$ -open set;
- (6).  $\psi$ -closed set [9, 19] if  $scl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $sg$ -open in  $X$ . The complement of  $\Psi$ -closed set is called  $\Psi$ -open set;
- (7). a  $A$ -closed set [11] if  $cl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $\check{g}$ -open in  $X$ . The complement of  $A$ -closed set is called  $A$ -open set;
- (8). a  $B$ -closed set [11] if  $scl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $A$ -open in  $X$ . The complement of  $B$ -closed set is called  $B$ -open set;
- (9). a  $\check{g}$ -closed set [11] if  $cl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $B$ -open in  $X$ . The complement of  $\check{g}$ -closed set is called  $\check{g}$ -open set.

The collection of all  $\check{g}$ -closed sets of  $X$  is denoted by  $\check{g}C(X)$ .

**Definition 2.3** ([12]).

- (1). For any  $A \subseteq X$ ,  $\check{g}\text{-int}(A)$  is defined as the union of all  $\check{g}$ -open sets contained in  $A$ . In symbols,  $\check{g}\text{-int}(A) = \cup\{G : G \subseteq A \text{ and } G \text{ is } \check{g}\text{-open}\}$ .
- (2). For every set  $A \subseteq X$ , we define the  $\check{g}$ -closure of  $A$  to be the intersection of all  $\check{g}$ -closed sets containing  $A$ . In symbols,  $\check{g}\text{-cl}(A) = \cap\{F : A \subseteq F \in \check{g}C(X)\}$ .

**Definition 2.4** ([12]). Let  $\tau_{\check{g}}$  be the topology on  $X$  generated by  $\check{g}$ -closure in the usual manner. That is,  $\tau_{\check{g}} = \{U \subseteq X : \check{g}\text{-cl}(U^c) = U^c\}$ .

**Definition 2.5** ([13]). Let  $(X, \tau)$  be a topological space. Let  $x$  be a point of  $X$  and  $G$  be a subset of  $X$ . Then  $G$  is called an  $\check{g}$ -neighborhood of  $x$  (briefly,  $\check{g}$ -nbhd of  $x$ ) in  $X$  if there exists an  $\check{g}$ -open set  $U$  of  $X$  such that  $x \in U \subseteq G$ .

**Definition 2.6.** A space  $X$  is called

- (1).  $T_\omega$ -space if every  $\omega$ -closed set in it is closed [16].
- (2).  $T_{\check{g}}$ -space if every  $\check{g}$ -closed set in it is closed [15].

**Definition 2.7.** A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is called

- (1).  $\omega$ -continuous [16] if the inverse image of every closed set in  $(Y, \sigma)$  is  $\omega$ -closed in  $(X, \tau)$ .
- (2).  $\check{g}$ -continuous [14] if the inverse image of every closed set in  $(Y, \sigma)$  is  $\check{g}$ -closed in  $(X, \tau)$ .
- (3).  $\check{g}$ -irresolute [14] if the inverse image of every  $\check{g}$ -closed set in  $(Y, \sigma)$  is  $\check{g}$ -closed in  $(X, \tau)$ .
- (4). strongly  $\check{g}$ -continuous [14] if the inverse image of every  $\check{g}$ -open set in  $(Y, \sigma)$  is open in  $(X, \tau)$ .
- (5).  $B$ -irresolute [14] if  $f^{-1}(V)$  is  $B$ -open in  $(X, \tau)$  for every  $B$ -open subset  $V$  in  $(Y, \sigma)$ .

**Proposition 2.8** ([12]). For any  $A \subseteq X$ , the following hold:

- (1).  $\check{g}\text{-int}(A)$  is the largest  $\check{g}$ -open set contained in  $A$ .
- (2).  $A$  is  $\check{g}$ -open if and only if  $\check{g}\text{-int}(A) = A$ .

**Proposition 2.9** ([12]). For any  $A \subseteq X$ , the following hold:

- (1).  $\check{g}\text{-cl}(A)$  is the smallest  $\check{g}$ -closed set containing  $A$ .
- (2).  $A$  is  $\check{g}$ -closed if and only if  $\check{g}\text{-cl}(A) = A$ .

**Proposition 2.10** ([12]). For any two subsets  $A$  and  $B$  of  $(X, \tau)$ , the following hold:

- (1). If  $A \subseteq B$ , then  $\check{g}\text{-cl}(A) \subseteq \check{g}\text{-cl}(B)$ .
- (2).  $\check{g}\text{-cl}(A \cap B) \subseteq \check{g}\text{-cl}(A) \cap \check{g}\text{-cl}(B)$ .

**Theorem 2.11** ([14]). A subset  $A$  of  $X$  is  $\check{g}$ -open if and only if  $F \subseteq \text{int}(A)$  whenever  $F$  is  $B$ -closed and  $F \subseteq A$ .

**Definition 2.12.** A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is called

- (1).  $g$ -closed [8] if  $f(V)$  is  $g$ -closed in  $(Y, \sigma)$  for every closed set  $V$  of  $(X, \tau)$ .
- (2).  $sg$ -closed [5] if  $f(V)$  is  $sg$ -closed in  $(Y, \sigma)$  for every closed set  $V$  of  $(X, \tau)$ .
- (3).  $gs$ -closed [5] if  $f(V)$  is  $gs$ -closed in  $(Y, \sigma)$  for every closed set  $V$  of  $(X, \tau)$ .
- (4).  $\psi$ -closed [9] if  $f(V)$  is  $\psi$ -closed in  $(Y, \sigma)$  for every closed set  $V$  of  $(X, \tau)$ .

### 3. $\check{g}$ -closed Maps

We introduce the following definition:

**Definition 3.1.** A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\check{g}$ -closed if the image of every closed set in  $(X, \tau)$  is  $\check{g}$ -closed in  $(Y, \sigma)$ .

**Example 3.2.** Let  $X = Y = \{a, b, c\}$  with  $\tau = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$  and  $\sigma = \{\phi, \{a, b\}, Y\}$ . Let  $f : (X, \tau) \rightarrow (Y, \sigma)$  be the identity map. Then  $f$  is an  $\check{g}$ -closed map.

**Proposition 3.3.** A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\check{g}$ -closed if and only if  $\check{g}\text{-cl}(f(A)) \subseteq f(\text{cl}(A))$  for every subset  $A$  of  $(X, \tau)$ .

*Proof.* Suppose that  $f$  is  $\check{g}$ -closed and  $A \subseteq X$ . Then  $\text{cl}(A)$  is closed in  $X$  and so  $f(\text{cl}(A))$  is  $\check{g}$ -closed in  $(Y, \sigma)$ . We have  $f(A) \subseteq f(\text{cl}(A))$  and by Propositions 2.9 and 2.10,  $\check{g}\text{-cl}(f(A)) \subseteq \check{g}\text{-cl}(f(\text{cl}(A))) = f(\text{cl}(A))$ .

Conversely, let  $A$  be any closed set in  $(X, \tau)$ . Then  $A = \text{cl}(A)$  and so  $f(A) = f(\text{cl}(A)) \supseteq \check{g}\text{-cl}(f(A))$ , by hypothesis. We have  $f(A) \subseteq \check{g}\text{-cl}(f(A))$ . Therefore  $f(A) = \check{g}\text{-cl}(f(A))$ . i.e.,  $f(A)$  is  $\check{g}$ -closed by Proposition 2.9 and hence  $f$  is  $\check{g}$ -closed.  $\square$

**Proposition 3.4.** *Let  $f : (X, \tau) \rightarrow (Y, \sigma)$  be a map such that  $\check{g}\text{-cl}(f(A)) \subseteq f(\text{cl}(A))$  for every subset  $A \subseteq X$ . Then the image  $f(A)$  of a closed set  $A$  in  $(X, \tau)$  is  $\check{g}$ -closed in  $(Y, \sigma)$ .*

*Proof.* Let  $A$  be a closed set in  $(X, \tau)$ . Then by hypothesis  $\check{g}\text{-cl}(f(A)) \subseteq f(\text{cl}(A)) = f(A)$  and so  $\check{g}\text{-cl}(f(A)) = f(A)$ . Therefore  $f(A)$  is  $\check{g}$ -closed in  $(Y, \sigma)$ . □

**Theorem 3.5.** *A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\check{g}$ -closed if and only if for each subset  $S$  of  $(Y, \sigma)$  and each open set  $U$  containing  $f^{-1}(S)$  there is an  $\check{g}$ -open set  $V$  of  $(Y, \sigma)$  such that  $S \subseteq V$  and  $f^{-1}(V) \subseteq U$ .*

*Proof.* Suppose  $f$  is  $\check{g}$ -closed. Let  $S \subseteq Y$  and  $U$  be an open set of  $(X, \tau)$  such that  $f^{-1}(S) \subseteq U$ . Then  $V = (f(U^c))^c$  is an  $\check{g}$ -open set containing  $S$  such that  $f^{-1}(V) \subseteq U$ .

For the converse, let  $F$  be a closed set of  $(X, \tau)$ . Then  $f^{-1}((f(F))^c) \subseteq F^c$  and  $F^c$  is open. By assumption, there exists an  $\check{g}$ -open set  $V$  in  $(Y, \sigma)$  such that  $(f(F))^c \subseteq V$  and  $f^{-1}(V) \subseteq F^c$  and so  $F \subseteq (f^{-1}(V))^c$ . Hence  $V^c \subseteq f(F) \subseteq f((f^{-1}(V))^c) \subseteq V^c$  which implies  $f(F) = V^c$ . Since  $V^c$  is  $\check{g}$ -closed,  $f(F)$  is  $\check{g}$ -closed and therefore  $f$  is  $\check{g}$ -closed. □

**Proposition 3.6.** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is B-irresolute  $\check{g}$ -closed and  $A$  is an  $\check{g}$ -closed subset of  $(X, \tau)$ , then  $f(A)$  is  $\check{g}$ -closed in  $(Y, \sigma)$ .*

*Proof.* Let  $U$  be an B-open set in  $(Y, \sigma)$  such that  $f(A) \subseteq U$ . Since  $f$  is B-irresolute,  $f^{-1}(U)$  is an B-open set containing  $A$ . Hence  $\text{cl}(A) \subseteq f^{-1}(U)$  as  $A$  is  $\check{g}$ -closed in  $(X, \tau)$ . Since  $f$  is  $\check{g}$ -closed,  $f(\text{cl}(A))$  is an  $\check{g}$ -closed set contained in the B-open set  $U$ , which implies that  $\text{cl}(f(\text{cl}(A))) \subseteq U$  and hence  $\text{cl}(f(A)) \subseteq U$ . Therefore,  $f(A)$  is an  $\check{g}$ -closed set in  $(Y, \sigma)$ . □

The following example shows that the composition of two  $\check{g}$ -closed maps need not be a  $\check{g}$ -closed.

**Example 3.7.** *Let  $(X, \tau)$ ,  $(Y, \sigma)$  and  $f$  be as in Example 3.2. Let  $Z = \{a, b, c\}$  and  $\eta = \{\phi, \{a\}, \{a, b\}, Z\}$ . Let  $g : (Y, \sigma) \rightarrow (Z, \eta)$  be the identity map. Then both  $f$  and  $g$  are  $\check{g}$ -closed maps but their composition  $g \circ f : (X, \tau) \rightarrow (Z, \eta)$  is not an  $\check{g}$ -closed map, since for the closed set  $\{a, c\}$  in  $(X, \tau)$ ,  $(g \circ f)(\{a, c\}) = \{a, c\}$ , which is not an  $\check{g}$ -closed set in  $(Z, \eta)$ .*

**Corollary 3.8.** *Let  $f : (X, \tau) \rightarrow (Y, \sigma)$  be  $\check{g}$ -closed and  $g : (Y, \sigma) \rightarrow (Z, \eta)$  be  $\check{g}$ -closed and B-irresolute, then their composition  $g \circ f : (X, \tau) \rightarrow (Z, \eta)$  is  $\check{g}$ -closed.*

*Proof.* Let  $A$  be a closed set of  $(X, \tau)$ . Then by hypothesis  $f(A)$  is an  $\check{g}$ -closed set in  $(Y, \sigma)$ . Since  $g$  is both  $\check{g}$ -closed and B-irresolute by Proposition 3.6,  $g(f(A)) = (g \circ f)(A)$  is  $\check{g}$ -closed in  $(Z, \eta)$  and therefore  $g \circ f$  is  $\check{g}$ -closed. □

**Proposition 3.9.** *Let  $f : (X, \tau) \rightarrow (Y, \sigma)$  and  $g : (Y, \sigma) \rightarrow (Z, \eta)$  be  $\check{g}$ -closed maps where  $(Y, \sigma)$  is a  $T_{\check{g}}$ -space. Then their composition  $g \circ f : (X, \tau) \rightarrow (Z, \eta)$  is  $\check{g}$ -closed.*

*Proof.* Let  $A$  be a closed set of  $(X, \tau)$ . Then by assumption  $f(A)$  is  $\check{g}$ -closed in  $(Y, \sigma)$ . Since  $(Y, \sigma)$  is a  $T_{\check{g}}$ -space,  $f(A)$  is closed in  $(Y, \sigma)$  and again by assumption  $g(f(A))$  is  $\check{g}$ -closed in  $(Z, \eta)$ . i.e.,  $(g \circ f)(A)$  is  $\check{g}$ -closed in  $(Z, \eta)$  and so  $g \circ f$  is  $\check{g}$ -closed. □

**Proposition 3.10.** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\check{g}$ -closed,  $g : (Y, \sigma) \rightarrow (Z, \eta)$  is  $\check{g}$ -closed, (resp.  $\psi$ -closed,  $sg$ -closed and  $gs$ -closed) and  $(Y, \sigma)$  is a  $T_{\check{g}}$ -space, then their composition  $g \circ f : (X, \tau) \rightarrow (Z, \eta)$  is  $g$ -closed (resp.  $\psi$ -closed,  $sg$ -closed and  $gs$ -closed).*

*Proof.* Let  $A$  be a closed set of  $(X, \tau)$ . Then by assumption  $f(A)$  is  $\check{g}$ -closed in  $(Y, \sigma)$ . Since  $(Y, \sigma)$  is a  $T_{\check{g}}$ -space,  $f(A)$  is closed in  $(Y, \sigma)$  and again by assumption  $g(f(A))$  is  $g$ -closed (resp.  $\psi$ -closed,  $sg$ -closed and  $gs$ -closed) in  $(Z, \eta)$ . i.e.,  $(g \circ f)(A)$  is  $g$ -closed (resp.  $\psi$ -closed,  $sg$ -closed and  $gs$ -closed) in  $(Z, \eta)$  and so  $g \circ f$  is  $g$ -closed (resp.  $\psi$ -closed,  $sg$ -closed and  $gs$ -closed). □

**Proposition 3.11.** *Let  $f : (X, \tau) \rightarrow (Y, \sigma)$  be a closed map and  $g : (Y, \sigma) \rightarrow (Z, \eta)$  be an  $\check{g}$ -closed map, then their composition  $g \circ f : (X, \tau) \rightarrow (Z, \eta)$  is  $\check{g}$ -closed.*

*Proof.* Let  $A$  be a closed set of  $(X, \tau)$ . Then by assumption  $f(A)$  is closed in  $(Y, \sigma)$  and again by assumption  $g(f(A))$  is  $\check{g}$ -closed in  $(Z, \eta)$ . i.e.,  $(g \circ f)(A)$  is  $\check{g}$ -closed in  $(Z, \eta)$  and so  $g \circ f$  is  $\check{g}$ -closed.  $\square$

**Remark 3.12.** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is an  $\check{g}$ -closed and  $g : (Y, \sigma) \rightarrow (Z, \eta)$  is closed, then their composition need not be an  $\check{g}$ -closed map as seen from the following example.*

**Example 3.13.** *Let  $(X, \tau)$ ,  $(Y, \sigma)$  and  $f$  be as in Example 3.2. Let  $Z = \{a, b, c\}$  and  $\eta = \{\phi, \{a\}, \{a, b\}, Z\}$ . Let  $g : (Y, \sigma) \rightarrow (Z, \eta)$  be the identity map. Then  $f$  is an  $\check{g}$ -closed map and  $g$  is a closed map. But their composition  $g \circ f : (X, \tau) \rightarrow (Z, \eta)$  is not an  $\check{g}$ -closed map, since for the closed set  $\{a, c\}$  in  $(X, \tau)$ ,  $(g \circ f)(\{a, c\}) = \{a, c\}$ , which is not an  $\check{g}$ -closed set in  $(Z, \eta)$ .*

**Theorem 3.14.** *Let  $f : (X, \tau) \rightarrow (Y, \sigma)$  and  $g : (Y, \sigma) \rightarrow (Z, \eta)$  be two maps such that their composition  $g \circ f : (X, \tau) \rightarrow (Z, \eta)$  is an  $\check{g}$ -closed map. Then the following statements are true.*

- (1). *If  $f$  is continuous and surjective, then  $g$  is  $\check{g}$ -closed.*
- (2). *If  $g$  is  $\check{g}$ -irresolute and injective, then  $f$  is  $\check{g}$ -closed.*
- (3). *If  $f$  is  $\omega$ -continuous, surjective and  $(X, \tau)$  is a  $T_\omega$ -space, then  $g$  is  $\check{g}$ -closed.*
- (4). *If  $g$  is strongly  $\check{g}$ -continuous and injective, then  $f$  is closed.*

*Proof.* (1). Let  $A$  be a closed set of  $(Y, \sigma)$ . Since  $f$  is continuous,  $f^{-1}(A)$  is closed in  $(X, \tau)$  and since  $g \circ f$  is  $\check{g}$ -closed,  $(g \circ f)(f^{-1}(A))$  is  $\check{g}$ -closed in  $(Z, \eta)$ . That is  $g(A)$  is  $\check{g}$ -closed in  $(Z, \eta)$ , since  $f$  is surjective. Therefore  $g$  is an  $\check{g}$ -closed map.

(2). Let  $B$  be a closed set of  $(X, \tau)$ . Since  $g \circ f$  is  $\check{g}$ -closed,  $(g \circ f)(B)$  is  $\check{g}$ -closed in  $(Z, \eta)$ . Since  $g$  is  $\check{g}$ -irresolute,  $g^{-1}((g \circ f)(B))$  is  $\check{g}$ -closed set in  $(Y, \sigma)$ . That is  $f(B)$  is  $\check{g}$ -closed in  $(Y, \sigma)$ , since  $g$  is injective. Thus  $f$  is an  $\check{g}$ -closed map.

(3). Let  $C$  be a closed set of  $(Y, \sigma)$ . Since  $f$  is  $\omega$ -continuous,  $f^{-1}(C)$  is  $\omega$ -closed in  $(X, \tau)$ . Since  $(X, \tau)$  is a  $T_\omega$ -space,  $f^{-1}(C)$  is closed in  $(X, \tau)$  and so as in (1),  $g$  is an  $\check{g}$ -closed map.

(4). Let  $D$  be a closed set of  $(X, \tau)$ . Since  $g \circ f$  is  $\check{g}$ -closed,  $(g \circ f)(D)$  is  $\check{g}$ -closed in  $(Z, \eta)$ . Since  $g$  is strongly  $\check{g}$ -continuous,  $g^{-1}((g \circ f)(D))$  is closed in  $(Y, \sigma)$ . That is  $f(D)$  is closed set in  $(Y, \sigma)$ , since  $g$  is injective. Therefore  $f$  is a closed map.  $\square$

In the next theorem we show that normality is preserved under continuous  $\check{g}$ -closed maps.

**Theorem 3.15.** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is a continuous,  $\check{g}$ -closed map from a normal space  $(X, \tau)$  onto a space  $(Y, \sigma)$ , then  $(Y, \sigma)$  is normal.*

*Proof.* Let  $A$  and  $B$  be two disjoint closed subsets of  $(Y, \sigma)$ . Since  $f$  is continuous,  $f^{-1}(A)$  and  $f^{-1}(B)$  are disjoint closed sets of  $(X, \tau)$ . Since  $(X, \tau)$  is normal, there exist disjoint open sets  $U$  and  $V$  of  $(X, \tau)$  such that  $f^{-1}(A) \subseteq U$  and  $f^{-1}(B) \subseteq V$ . Since  $f$  is  $\check{g}$ -closed, by Theorem 3.5, there exist disjoint  $\check{g}$ -open sets  $G$  and  $H$  in  $(Y, \sigma)$  such that  $A \subseteq G$ ,  $B \subseteq H$ ,  $f^{-1}(G) \subseteq U$  and  $f^{-1}(H) \subseteq V$ . Since  $U$  and  $V$  are disjoint,  $\text{int}(G)$  and  $\text{int}(H)$  are disjoint open sets in  $(Y, \sigma)$ . Since  $A$  is closed,  $A$  is  $B$ -closed and therefore we have by Theorem 2.11,  $A \subseteq \text{int}(G)$ . Similarly  $B \subseteq \text{int}(H)$  and hence  $(Y, \sigma)$  is normal.  $\square$

Analogous to an  $\check{g}$ -closed map, we define an  $\check{g}$ -open map as follows:

**Definition 3.16.** A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be an  $\check{g}$ -open map if the image  $f(A)$  is  $\check{g}$ -open in  $(Y, \sigma)$  for each open set  $A$  in  $(X, \tau)$ .

**Proposition 3.17.** For any bijection  $f : (X, \tau) \rightarrow (Y, \sigma)$ , the following statements are equivalent:

- (1).  $f^{-1} : (Y, \sigma) \rightarrow (X, \tau)$  is  $\check{g}$ -continuous.
- (2).  $f$  is  $\check{g}$ -open map.
- (3).  $f$  is  $\check{g}$ -closed map.

*Proof.* (1)  $\Rightarrow$  (2) Let  $U$  be an open set of  $(X, \tau)$ . By assumption,  $(f^{-1})^{-1}(U) = f(U)$  is  $\check{g}$ -open in  $(Y, \sigma)$  and so  $f$  is  $\check{g}$ -open.  
 (2)  $\Rightarrow$  (3) Let  $F$  be a closed set of  $(X, \tau)$ . Then  $F^c$  is open set in  $(X, \tau)$ . By assumption,  $f(F^c)$  is  $\check{g}$ -open in  $(Y, \sigma)$ . That is  $f(F^c) = (f(F))^c$  is  $\check{g}$ -open in  $(Y, \sigma)$  and therefore  $f(F)$  is  $\check{g}$ -closed in  $(Y, \sigma)$ . Hence  $f$  is  $\check{g}$ -closed.  
 (3)  $\Rightarrow$  (1) Let  $F$  be a closed set of  $(X, \tau)$ . By assumption,  $f(F)$  is  $\check{g}$ -closed in  $(Y, \sigma)$ . But  $f(F) = (f^{-1})^{-1}(F)$  and therefore  $f^{-1}$  is  $\check{g}$ -continuous. □

In the next two theorems, we obtain various characterizations of  $\check{g}$ -open maps.

**Theorem 3.18.** Assume that the collection of all  $\check{g}$ -open sets of  $Y$  is closed under arbitrary union. Let  $f : (X, \tau) \rightarrow (Y, \sigma)$  be a map. Then the following statements are equivalent:

- (1).  $f$  is an  $\check{g}$ -open map.
- (2). For a subset  $A$  of  $(X, \tau)$ ,  $f(\text{int}(A)) \subseteq \check{g}\text{-int}(f(A))$ .
- (3). For each  $x \in X$  and for each neighborhood  $U$  of  $x$  in  $(X, \tau)$ , there exists an  $\check{g}$ -neighborhood  $W$  of  $f(x)$  in  $(Y, \sigma)$  such that  $W \subseteq f(U)$ .

*Proof.* (1)  $\Rightarrow$  (2). Suppose  $f$  is  $\check{g}$ -open. Let  $A \subseteq X$ . Then  $\text{int}(A)$  is open in  $(X, \tau)$  and so  $f(\text{int}(A))$  is  $\check{g}$ -open in  $(Y, \sigma)$ . We have  $f(\text{int}(A)) \subseteq f(A)$ . Therefore by Proposition 2.8,  $f(\text{int}(A)) \subseteq \check{g}\text{-int}(f(A))$ .  
 (2)  $\Rightarrow$  (3). Suppose (2) holds. Let  $x \in X$  and  $U$  be an arbitrary neighborhood of  $x$  in  $(X, \tau)$ . Then there exists an open set  $G$  such that  $x \in G \subseteq U$ . By assumption,  $f(G) = f(\text{int}(G)) \subseteq \check{g}\text{-int}(f(G))$ . This implies  $f(G) = \check{g}\text{-int}(f(G))$ . By Proposition 2.8, we have  $f(G)$  is  $\check{g}$ -open in  $(Y, \sigma)$ . Further,  $f(x) \in f(G) \subseteq f(U)$  and so (3) holds, by taking  $W = f(G)$ .  
 (3)  $\Rightarrow$  (1). Suppose (3) holds. Let  $U$  be any open set in  $(X, \tau)$ ,  $x \in U$  and  $f(x) = y$ . Then  $y \in f(U)$  and for each  $y \in f(U)$ , by assumption there exists an  $\check{g}$ -neighborhood  $W_y$  of  $y$  in  $(Y, \sigma)$  such that  $W_y \subseteq f(U)$ . Since  $W_y$  is an  $\check{g}$ -neighborhood of  $y$ , there exists an  $\check{g}$ -open set  $V_y$  in  $(Y, \sigma)$  such that  $y \in V_y \subseteq W_y$ . Therefore,  $f(U) = \cup \{V_y : y \in f(U)\}$  is an  $\check{g}$ -open set in  $(Y, \sigma)$  by the given condition. Thus  $f$  is an  $\check{g}$ -open map. □

**Theorem 3.19.** A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\check{g}$ -open if and only if for any subset  $S$  of  $(Y, \sigma)$  and for any closed set  $F$  containing  $f^{-1}(S)$ , there exists an  $\check{g}$ -closed set  $K$  of  $(Y, \sigma)$  containing  $S$  such that  $f^{-1}(K) \subseteq F$ .

*Proof.* Similar to Theorem 3.5. □

**Corollary 3.20.** A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\check{g}$ -open if and only if  $f^{-1}(\check{g}\text{-cl}(B)) \subseteq \text{cl}(f^{-1}(B))$  for each subset  $B$  of  $(Y, \sigma)$ .

*Proof.* Suppose that  $f$  is  $\check{g}$ -open. Then for any  $B \subseteq Y$ ,  $f^{-1}(B) \subseteq \text{cl}(f^{-1}(B))$ . By Theorem 3.19, there exists an  $\check{g}$ -closed set  $K$  of  $(Y, \sigma)$  such that  $B \subseteq K$  and  $f^{-1}(K) \subseteq \text{cl}(f^{-1}(B))$ . Therefore,  $f^{-1}(\check{g}\text{-cl}(B)) \subseteq (f^{-1}(K)) \subseteq \text{cl}(f^{-1}(B))$ , since  $K$  is an  $\check{g}$ -closed set in  $(Y, \sigma)$ .

Conversely, let  $S$  be any subset of  $(Y, \sigma)$  and  $F$  be any closed set containing  $f^{-1}(S)$ . Put  $K = \check{g}\text{-cl}(S)$ . Then  $K$  is an  $\check{g}$ -closed set and  $S \subseteq K$ . By assumption,  $f^{-1}(K) = f^{-1}(\check{g}\text{-cl}(S)) \subseteq \text{cl}(f^{-1}(S)) \subseteq F$  and therefore by Theorem 3.19,  $f$  is  $\check{g}$ -open. □

Finally in this section, we define another new class of maps called  $\check{g}^*$ -closed maps which are stronger than  $\check{g}$ -closed maps.

**Definition 3.21.** A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\check{g}^*$ -closed if the image  $f(A)$  is  $\check{g}$ -closed in  $(Y, \sigma)$  for every  $\check{g}$ -closed set  $A$  in  $(X, \tau)$ .

For example the map  $f$  in Example 3.2 is an  $\check{g}^*$ -closed map. Analogous to  $\check{g}^*$ -closed map we can also define  $\check{g}^*$ -open map.

**Remark 3.22.** Since every closed set is an  $\check{g}$ -closed set we have  $\check{g}^*$ -closed map is an  $\check{g}$ -closed map. The converse is not true in general as seen from the following example.

**Example 3.23.** Let  $X = Y = \{a, b, c\}$  with  $\tau = \{\phi, \{a, b\}, X\}$  and  $\sigma = \{\phi, \{a\}, \{a, b\}, Y\}$ . Let  $f : (X, \tau) \rightarrow (Y, \sigma)$  be the identity map. Then  $f$  is an  $\check{g}$ -closed but not  $\check{g}^*$ -closed map. Since  $\{a, c\}$  is  $\check{g}$ -closed set in  $(X, \tau)$ , but its image under  $f$  is  $\{a, c\}$  which is not  $\check{g}$ -closed set in  $(Y, \sigma)$ .

**Proposition 3.24.** A map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\check{g}^*$ -closed if and only if  $\check{g}\text{-cl}(f(A)) \subseteq f(\check{g}\text{-cl}(A))$  for every subset  $A$  of  $(X, \tau)$ .

*Proof.* Similar to Proposition 3.3. □

**Proposition 3.25.** For any bijection  $f : (X, \tau) \rightarrow (Y, \sigma)$ , the following statements are equivalent:

- (1).  $f^{-1} : (Y, \sigma) \rightarrow (X, \tau)$  is  $\check{g}$ -irresolute.
- (2).  $f$  is  $\check{g}^*$ -open map.
- (3).  $f$  is  $\check{g}^*$ -closed map.

*Proof.* Similar to Proposition 3.17. □

**Proposition 3.26.** If a map  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $B$ -irresolute and  $\check{g}$ -closed, then it is an  $\check{g}^*$ -closed map.

*Proof.* The proof follows from Proposition 3.6. □

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